

KeY: environment for verification of JavaCard programs.

- Subset of Java for smartcard applications and embedded systems.
- Universities of Karlsruhe, Koblenz, Chalmers, 1998–
 - Beckert et al: "Deductive Software Verification The KeY Book: From Theory to Practice", Springer, 2016.
 - Chapter 16: Formal Verification with KeY: A Tutorial"
- Specification languages: OCL and JML.
 - Original: OCL (Object Constraint Language), part of UML standard.
 - Later added: JML (Java Modeling Language).
- Logical framework: Dynamic Logic (DL).
 - Successor/generalization of Hoare Logic.
 - Integrated prover with interfaces to external decision procedures.
 - Simplify, CVC3, CVC4, Yices, Z3.

Now only JML is supported as a specification language.

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Verifying Java Programs



Extended static checking of Java programs: Even if no error is reported, a program may violate its specification. Unsound calculus for verifying while loops. Even correct programs may trigger error reports: Incomplete calculus for verifying while loops. Incomplete calculus in automatic decision procedure (Simplify). Verification of Java programs: Sound verification calculus. Not unfolding of loops, but loop reasoning based on invariants. Loop invariants must be typically provided by user. Automatic generation of verification conditions. From JML-annotated Java program, proof obligations are derived. Human-guided proofs of these conditions (using a proof assistant). Simple conditions automatically proved by automatic procedure. We will now deal with an integrated environment for this purpose. 1/19Wolfgang Schreiner http://www.risc.jku.at **Dynamic Logic** Further development of Hoare Logic to a modal logic. Hoare logic: two separate kinds of statements. Formulas P, Q constraining program states.

- Hoare triples {*P*}*C*{*Q*} constraining state transitions.
- Dynamic logic: single kind of statement.
 - Predicate logic formulas extended by two kinds of modalities.
 - $[C]Q (\Leftrightarrow \neg \langle C \rangle \neg Q)$
 - Every state that can be reached by the execution of *C* satisfies *Q*.
 - The statement is trivially true, if *C* does not terminate.
 - $\langle C \rangle Q (\Leftrightarrow \neg [C] \neg Q)$
 - There exists some state that can be reached by the execution of *C* and that satisfies *Q*.
 - The statement is only true, if C terminates.

States and state transitions can be described by DL formulas.

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Dynamic Logic versus Hoare Logic



Hoare triple $\{P\}C\{Q\}$ can be expressed as a DL formula.

- Partial correctness interpretation: $P \Rightarrow [C]Q$
 - If P holds in the current state and the execution of C reaches another state, then Q holds in that state.
 - Equivalent to the partial correctness interpretation of $\{P\}C\{Q\}$.
- Total correctness interpretation: $P \Rightarrow \langle C \rangle Q$
 - If P holds in the current state, then there exists another state that can be reached by the execution of C in which Q holds.
 - If C is deterministic, there exists at most one such state; then equivalent to the total correctness interpretation of {P}C{Q}.

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For deterministic programs, the interpretations coincide.



Modal formulas can also occur in the context of quantifiers.

- Hoare Logic: $\{x = a\}$ y:=x*x $\{x = a \land y = a^2\}$
 - Use of free mathematical variable *a* to denote the "old" value of *x*.
- Dynamic logic: $\forall a : x = a \Rightarrow [y := x * x] x = a \land y = a^2$
 - Quantifiers can be used to restrict the scopes of mathematical variables across state transitions.

Set of DL formulas is closed under the usual logical operations.

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A Calculus for Dynamic Logic

Basic rules:

- Rules for predicate logic extended by general rules for modalities.
- Command-related rules: • $\frac{\Gamma \vdash F[T/X]}{\Gamma \vdash [X := T]F}$ • $\frac{\Gamma \vdash [C_1][C_2]F}{\Gamma \vdash [C_1; C_2]F}$ • $\frac{\Gamma \vdash [C_1]F \quad \Gamma \vdash [C_2]F}{\Gamma \vdash [C_1 \cup C_2]F}$ • $\frac{\Gamma \vdash F \Rightarrow [C]F}{\Gamma \vdash F \Rightarrow [C^*]F}$ • $\frac{\Gamma \vdash F \Rightarrow G}{\Gamma \vdash [F?]G}$

From these, Hoare-like rules for the high-level language can be derived

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A core language of commands (non-deterministic):
X := T assignment

A Calculus for Dynamic Logic

X := I	assignment	
<i>C</i> ₁ ; <i>C</i> ₂	sequential co	mposition
$\mathcal{C}_1\cup\mathcal{C}_2$	non-determin	istic choice
<i>C</i> *	iteration (zer	o or more times)
F?	test (blocks i	f F is false)
A high-level la	nguage of comm	ands (deterministic):
skip	=	true?
abort	=	false?
X := T		
<i>C</i> ₁ ; <i>C</i> ₂		

=	$(F?; C_1) \cup ((\neg F)?; C_2)$
=	$(F?; C) \cup (\neg F)?$
=	$(F?; C)^*; (\neg F)?$
	=

A calculus is defined for dynamic logic with the core command language.

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Objects and Updates



Calculus has to deal with the pointer semantics of Java objects.

- Aliasing: two variables o, o' may refer to the same object.
 - Field assignment o.a := T may also affect the value of o'.a.
- Update formulas: $\{o.a \leftarrow T\}F$
 - Truth value of F in state after the assignment o.a := T.
- Field assignment rule:

$$\frac{\Gamma \vdash \{o.a \leftarrow T\}F}{\Gamma \vdash [o.a := T]F}$$

Field access rule:

$$\frac{\Gamma, o = o' \vdash F(T) \quad \Gamma, o \neq o' \vdash F(o'.a)}{\Gamma \vdash \{o.a \leftarrow T\}F(o'.a)}$$

- Case distinction depending on whether *o* and *o*' refer to same object.
- Only applied as last resort (after all other rules of the calculus).

Considerable complication of verifications.

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A Simple Example

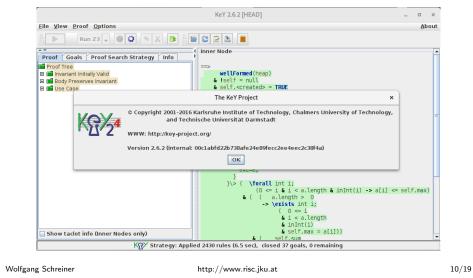
File/Load Example/Getting Started/Sum and Max

class	SumAndMax {	/*@ loop_invariant
int	<pre>sum; int max;</pre>	0 0 <= k && k <= a.length
/*@	requires (\forall int i;	<pre>@ && (\forall int i;</pre>
Q	0 <= i && i < a.length; 0 <= a[i]);	; @ 0 <= i && i < k; a[i] <= max)
Q	assignable sum, max;	@ && (k == 0 ==> max == 0)
Q	ensures (\forall int i;	<pre>@ && (k > 0 ==> (\exists int i;</pre>
Q	0 <= i && i < a.length; a[i] <= max	x); @ 0 <= i && i < k; max == a[i]))
Q	ensures (a.length > 0 ==>	<pre>@ && sum == (\sum int i;</pre>
Q	(\exists int i;	<pre>@ 0 <= i && i< k; a[i])</pre>
Q	0 <= i && i < a.length;	0 && sum <= k * max;
Q	<pre>max == a[i]));</pre>	<pre>@ assignable sum, max;</pre>
Q	ensures sum == (\sum int i;	<pre>@ decreases a.length - k;</pre>
Q	0 <= i && i < a.length; a[i]);	@*/
Q	<pre>ensures sum <= a.length * max;</pre>	<pre>while (k < a.length) {</pre>
@×	*/	if $(max < a[k]) max = a[k];$
void	d sumAndMax(int[] a) {	sum += a[k];
ຣເ	m = 0;	k++;
ma	ax = 0;	}
ir	nt k = 0;	
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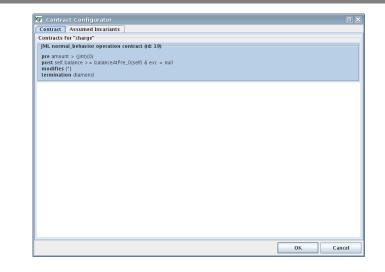
The JMLKeY Prover



> KeY &



A Simple Example (Contd)



Generate the proof obligations and choose one for verification.

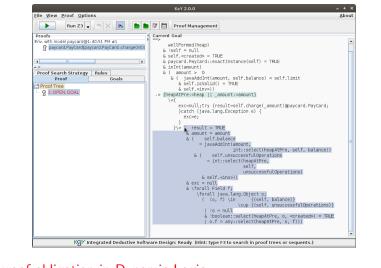
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A Simple Example (Contd'2)



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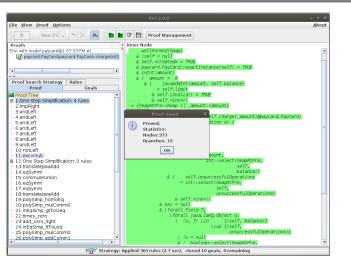


The proof obligation in Dynamic Logic.

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A Simple Example (Contd'4)



Proof runs through automatically.

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```
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```

}

A Simple Example (Contd'3)



wellFormed(heap)

==>

```
true
    & !self=null
    & . . .
   & (\forall int i; (0 <= i & i < a.length & inInt(i) -> 0 <= a[i])
      &(self.<inv> & !a = null))
 -> {heapAtPre:=heap || _a:=a}
     \<{
         exc=null;try {
           self.sumAndMax(_a)@SumAndMax;
         } catch (java.lang.Throwable e){ exc=e; }
       }\>(\forall int i;
                (0 <= i & i < a.length & inInt(i) -> a[i] <= self.max)
            & (( a.length > 0
                  -> \exists int i:
                       (0 <= i & i < a.length & inInt(i) & self.max = a[i]))
               & ( self.sum = javaCastInt(bsum{int i;}(0, a.length, a[i]))
                  & (self.sum <= javaMulInt(a.length, self.max) & self.<inv>)))
            & exc = null
            & \forall Field f;
                \forall java.lang.Object o;
                  ( (o, f) \in
                                    {(self,SumAndMax::$sum)}
                                \cup {(self,SumAndMax::$max)}
                   | !o = null
                   & !o.<created>@heapAtPre = TRUE
                   | o.f = o.f@heapAtPre))
Press button "Start" (green arrow)
```

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Linear Search

```
/*@ requires a != null;
     @ assignable \nothing;
     @ ensures
     0
          (\result == -1 &&
            (\forall int j; 0 <= j && j < a.length; a[j] != x)) ||
     0
          (0 <= \result && \result < a.length && a[\result] == x &&</pre>
     0
     Q
            (\forall int j; 0 <= j && j < \result; a[j] != x));</pre>
     @*/
   public static int search(int[] a, int x) {
     int n = a.length; int i = 0; int r = -1;
     /*@ loop_invariant
        @ a != null && n == a.length && 0 <= i && i <= n &&</pre>
          (\forall int j; 0 <= j && j < i; a[j] != x) &&
        0
        0 (r == -1 || (r == i && i < n && a[r] == x));</pre>
        @ decreases r == -1 ? n-i : 0;
        @ assignable r, i; // required by KeY, not legal JML
        @*/
     while (r == -1 \&\& i < n) {
        if (a[i] == x) r = i; else i = i+1;
     }
     return r;
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```

Linear Search (Contd)



Elle View Proof Options	Δb	out
🕨 Run Z3 🗸 🦘 🔀 🛅	Proof Management	
Proofs for with model (#22432 PH #) (for with model (#22432 PH #) (for with model (#22432 PH #) (for with the search ManOtisearch ((unt)) Proof Search Strategy Rules Proof Goals a root Tree a Room Recurdin (_b != nul) a Monta Recurdin (_b != nul) a Monta Recurdin (_b != nul)	<pre>image vellformed (near) wellformed (near) () = wellformed (nea</pre>	

Also this verification is completed automatically.

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Summary

- Various academic approaches to verifying Java(Card) programs.
 - Jack: http://www-sop.inria.fr/everest/soft/Jack/jack.html
 - Jive: http://www.pm.inf.ethz.ch/research/jive
 - Mobius: http://kindsoftware.com/products/opensource/Mobius/
- Do not yet scale to verification of full Java applications.
 - General language/program model is too complex.
 - Simplifying assumptions about program may be made.
 - Possibly only special properties may be verified.
- Nevertheless very helpful for reasoning on Java in the small.
 - Much beyond Hoare calculus on programs in toy languages.
 - Probably all examples in this course can be solved automatically by the use of the KeY prover and its integrated SMT solvers.
- Enforce clearer understanding of language features.
 - Perhaps constructs with complex reasoning are not a good idea...

In a not too distant future, customers might demand that some critical code is shipped with formal certificates (correctness proofs)...

Proof Structure



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Proof Search Strategy	Rules			
Proof	Goals			
🖬 Proof Tree				
Image:				
🗉 💼 Invariant Initially Valid				
🗉 💼 Body Preserves Invariant				
🗉 💼 Use Case				
🗉 💼 Null Reference (_a = null)				

- Multiple conditions:
 - Invariant initially valid.
 - Body preserves invariant.
 - Use case (invariant implies postcondition).
- If proof fails, elaborate which part causes trouble and potentially correct program, specification, loop annotations.

For a successful proof, in general multiple iterations of automatic proof search (button "Start") and invocation of separate SMT solvers required (button "Run Z3, Yices, CVC3, Simplify").

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