Specifying and Verifying Programs (Part 1)

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Specifying and Verifying Programs



We will discuss three (closely interrelated) calculi.

- Hoare Calculus: {P} c {Q}
 - If command *c* is executed in a pre-state with property *P* and terminates, it yields a post-state with property *Q*.

$${x = a \land y = b}x := x + y{x = a + y \land y = b}$$

- Predicate Transformers: wp(c, Q) = P
 - If the execution of command c shall yield a post-state with property Q, it must be executed in a pre-state with property P.

$$wp(x := x + y, x = a + y \land y = b) = (x + y = a + y \land y = b)$$

- State Relations: $c : [P \Rightarrow Q]^{x,...}$
 - The post-state generated by the execution of command c is related to the pre-state by $P \Rightarrow Q$ (where only variables x, \ldots have changed).

$$x = x + y$$
: [var $x = \text{old } x + \text{old } y$]^x



1. The Hoare Calculus

- 2. Predicate Transformers
- 3. Proving Verification Conditions
- 4. Termination
- 5. Abortion
- 6. Procedures

The Hoare Calculus



First and best-known calculus for program reasoning (C.A.R. Hoare).

- "Hoare triple": {P} c {Q}
 - Logical propositions P and Q, program command c.
 - The Hoare triple is itself a logical proposition.
 - The Hoare calculus gives rules for constructing true Hoare triples.
- Partial correctness interpretation of $\{P\}$ c $\{Q\}$:

"If c is executed in a state in which P holds, then it terminates in a state in which Q holds unless it aborts or runs forever."

- Program does not produce wrong result.
- But program also need not produce any result.
 - Abortion and non-termination are not (yet) ruled out.
- Total correctness interpretation of $\{P\}$ c $\{Q\}$:

"If c is executed in a state in which P holds, then it terminates in a state in which Q holds."

Program produces the correct result.

We will use the partial correctness interpretation for the moment.

Weakening and Strengthening



$$\frac{P \Rightarrow P' \quad \{P'\} \ c \ \{Q'\} \quad Q' \Rightarrow Q}{\{P\} \ c \ \{Q\}}$$

- Logical derivation: $\frac{A_1 A_2}{B}$
 - Forward: If we have shown A_1 and A_2 , then we have also shown B.
 - Backward: To show B, it suffices to show A_1 and A_2 .
- Interpretation of above sentence:
 - To show that, if *P* holds, then *Q* holds after executing *c*, it suffices to show this for a *P'* weaker than *P* and a *Q'* stronger than *Q*.

Precondition may be weakened, postcondition may be strengthened.

Special Commands



$$\{P\}$$
 skip $\{P\}$ {true} **abort** {false}

- The **skip** command does not change the state; if *P* holds before its execution, then *P* thus holds afterwards as well.
- The abort command aborts execution and thus trivially satisfies partial correctness.
 - Axiom implies $\{P\}$ abort $\{Q\}$ for arbitrary P, Q.

Useful commands for reasoning and program transformations.

Scalar Assignments



$${Q[e/x]} x := e {Q}$$

Syntax

- Variable x, expression e.
- $Q[e/x] \dots Q$ where every free occurrence of x is replaced by e.

Interpretation

- To make sure that Q holds for x after the assignment of e to x, it suffices to make sure that Q holds for e before the assignment.
- Partial correctness
 - Evaluation of e may abort.

$${x+3<5}$$
 $x := x+3$ ${x<5}$
 ${x<2}$ $x := x+3$ ${x<5}$

Array Assignments



$${Q[a[i \mapsto e]/a]} \ a[i] := e {Q}$$

- An array is modelled as a function $a: I \rightarrow V$.
 - Index set I. value set V.
 - $a[i] = e \dots$ array a contains at index i the value e.
- Term $a[i \mapsto e]$ ("array a updated by assigning value e to index i")
 - A new array that contains at index i the value e.
 - All other elements of the array are the same as in a.
- Thus array assignment becomes a special case of scalar assignment.
 - Think of "a[i] := e" as " $a := a[i \mapsto e]$ ".

$${a[i \mapsto x][1] > 0} \quad a[i] := x \quad {a[1] > 0}$$

Arrays are here considered as basic values (no pointer semantics).

Array Assignments



How to reason about $a[i \mapsto e]$?

$$Q[\underline{a[i \mapsto e]}[j]]$$

$$(i = j \Rightarrow Q[e]) \land (i \neq j \Rightarrow Q[a[j]])$$

Array Axioms

$$i = j \Rightarrow \underbrace{a[i \mapsto e][j]} = e$$

 $i \neq j \Rightarrow \underbrace{a[i \mapsto e]} [j] = a[j]$

$$\{\underline{a[i\mapsto x]}[1]>0\} \quad a[i]:=x \quad \{a[1]>0\}$$

$$\{(i=1\Rightarrow x>0) \land (i\neq 1\Rightarrow a[1]>0)\} \quad a[i]:=x \quad \{a[1]>0\}$$

Get rid of "array update terms" when applied to indices.

Command Sequences



$$\frac{\{P\}\ c_1\ \{R\}\ \{R\}\ c_2\ \{Q\}}{\{P\}\ c_1; c_2\ \{Q\}}$$

- Interpretation
 - To show that, if P holds before the execution of c_1 ; c_2 , then Q holds afterwards, it suffices to show for some R that
 - if P holds before c₁, that R holds afterwards, and that
 - if R holds before c_2 , then Q holds afterwards.
- Problem: find suitable R.
 - Easy in many cases (see later).

$$\frac{\{x+y-1>0\}\ y:=y-1\ \{x+y>0\}\ \{x+y>0\}\ x:=x+y\ \{x>0\}}{\{x+y-1>0\}\ y:=y-1; x:=x+y\ \{x>0\}}$$

The calculus itself does not indicate how to find intermediate property.

Conditionals



$$\frac{\{P \land b\} \ c_1 \ \{Q\} \ \{P \land \neg b\} \ c_2 \ \{Q\}}{\{P\} \ \text{if } b \ \text{then} \ c_1 \ \text{else} \ c_2 \ \{Q\}}$$
$$\frac{\{P \land b\} \ c \ \{Q\} \ (P \land \neg b) \Rightarrow Q}{\{P\} \ \text{if } b \ \text{then} \ c \ \{Q\}}$$

Interpretation

- To show that, if P holds before the execution of the conditional, then Q holds afterwards.
- it suffices to show that the same is true for each conditional branch, under the additional assumption that this branch is executed.

$$\frac{\{x \neq 0 \land x \geq 0\} \ y := x \ \{y > 0\} \ \ \{x \neq 0 \land x \not\geq 0\} \ y := -x \ \{y > 0\}}{\{x \neq 0\} \ \text{if} \ x \geq 0 \ \text{then} \ y := x \ \text{else} \ y := -x \ \{y > 0\}}$$

Loops



{true} **loop** {false}
$$\frac{\{I \land b\} \ c \ \{I\}}{\{I\} \ \text{while} \ b \ \text{do} \ c \ \{I \land \neg b\}}$$

Interpretation:

- The loop command does not terminate and thus trivially satisfies partial correctness.
 - Axiom implies $\{P\}$ loop $\{Q\}$ for arbitrary P, Q.
- If it is the case that
 - I holds before the execution of the **while**-loop and
 - I also holds after every iteration of the loop body,

then I holds also after the execution of the loop (together with the negation of the loop condition b).

- I is a loop invariant.
- Problem
 - Rule for **while**-loop does not have arbitrary pre/post-conditions P, Q.

In practice, we combine this rule with the strengthening/weakening-rule.

Loops (Generalized)



$$\frac{P \Rightarrow I \quad \{I \land b\} \ c \ \{I\} \quad (I \land \neg b) \Rightarrow Q}{\{P\} \text{ while } b \text{ do } c \ \{Q\}}$$

Interpretation:

- To show that, if before the execution of a while-loop the property P holds, after its termination the property Q holds, it suffices to show for some property I (the loop invariant) that
 - *I* holds before the loop is executed (i.e. that *P* implies *I*),
 - if I holds when the loop body is entered (i.e. if also b holds), that after the execution of the loop body I still holds,
 - when the loop terminates (i.e. if b does not hold), I implies Q.
- Problem: find appropriate loop invariant 1.
 - Strongest relationship between all variables modified in loop body.

The calculus itself does not indicate how to find suitable loop invariant.

Example



$$I :\Leftrightarrow s = \sum_{j=1}^{i-1} j \land 1 \le i \le n+1$$

$$(n \ge 0 \land i = 1 \land s = 0) \Rightarrow I$$

$$\{I \land i \le n\} \ s := s+i; i := i+1 \ \{I\}$$

$$(I \land i \le n) \Rightarrow s = \sum_{j=1}^{n} j$$

$$\{n \ge 0 \land i = 1 \land s = 0\} \text{ while } i \le n \text{ do } (s := s+i; i := i+1) \ \{s = \sum_{j=1}^{n} j\}$$

The invariant captures the "essence" of a loop; only by giving its invariant, a true understanding of a loop is demonstrated.



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Backward Reasoning



Implication of rule for command sequences and rule for assignments:

$$\frac{\{P\} \ c \ \{Q[e/x]\}}{\{P\} \ c; x := e \ \{Q\}}$$

Interpretation

- If the last command of a sequence is an assignment, we can remove the assignment from the proof obligation.
- By multiple application, assignment sequences can be removed from the back to the front.

Weakest Preconditions



A calculus for "backward reasoning" (E.W. Dijkstra).

- Predicate transformer wp
 - Function "wp" that takes a command c and a postcondition Q and returns a precondition.
 - Read wp(c, Q) as "the weakest precondition of c w.r.t. Q".
- ightharpoonup wp(c,Q) is a precondition for c that ensures Q as a postcondition.
 - Must satisfy $\{wp(c, Q)\}\ c\ \{Q\}$.
- wp(c, Q) is the weakest such precondition.
 - Take any P such that $\{P\}$ c $\{Q\}$.
 - Then $P \Rightarrow wp(c, Q)$.
- Consequence: $\{P\}$ c $\{Q\}$ iff $(P \Rightarrow wp(c, Q))$
 - We want to prove $\{P\}$ c $\{Q\}$.
 - We may prove $P \Rightarrow wp(c, Q)$ instead.

Verification is reduced to the calculation of weakest preconditions.

Weakest Preconditions



The weakest precondition of each program construct.

```
\begin{array}{l} \mathsf{wp}(\mathbf{skip},Q) = Q \\ \mathsf{wp}(\mathbf{abort},Q) = \mathsf{true} \\ \mathsf{wp}(x := e,Q) = Q[e/x] \\ \mathsf{wp}(c_1;c_2,Q) = \mathsf{wp}(c_1,\mathsf{wp}(c_2,Q)) \\ \mathsf{wp}(\mathbf{if}\ b\ \mathbf{then}\ c_1\ \mathbf{else}\ c_2,Q) = (b\Rightarrow \mathsf{wp}(c_1,Q)) \land (\neg b\Rightarrow \mathsf{wp}(c_2,Q)) \\ \mathsf{wp}(\mathbf{if}\ b\ \mathbf{then}\ c,Q) \Leftrightarrow (b\Rightarrow \mathsf{wp}(c,Q)) \land (\neg b\Rightarrow Q) \\ \mathsf{wp}(\mathbf{while}\ b\ \mathbf{do}\ c,Q) = \dots \end{array}
```

Loops represent a special problem (see later).

Forward Reasoning



Sometimes, we want to derive a postcondition from a given precondition.

$$\{P\} \ x := e \ \{\exists x_0 : P[x_0/x] \land x = e[x_0/x]\}$$

■ Forward Reasoning

- What is the maximum we know about the post-state of an assignment *x* := *e*, if the pre-state satisfies *P*?
- We know that P holds for some value x_0 (the value of x in the pre-state) and that x equals $e[x_0/x]$.

$$\{x \ge 0 \land y = a\}$$

$$x := x + 1$$

$$\{\exists x_0 : x_0 \ge 0 \land y = a \land x = x_0 + 1\}$$

$$(\Leftrightarrow (\exists x_0 : x_0 \ge 0 \land x = x_0 + 1) \land y = a)$$

$$(\Leftrightarrow x > 0 \land y = a)$$

Strongest Postcondition



A calculus for forward reasoning.

- Predicate transformer sp
 - Function "sp" that takes a precondition P and a command c and returns a postcondition.
 - Read sp(c, P) as "the strongest postcondition of c w.r.t. P".
- = sp(c, P) is a postcondition for c that is ensured by precondition P.
 - Must satisfy $\{P\}$ c $\{\operatorname{sp}(c, P)\}$.
- = sp(c, P) is the strongest such postcondition.
 - Take any P, Q such that $\{P\}$ c $\{Q\}$.
 - Then $sp(c, P) \Rightarrow Q$.
- Consequence: $\{P\}$ c $\{Q\}$ iff $(\operatorname{sp}(c, P) \Rightarrow Q)$.
 - We want to prove $\{P\}$ c $\{Q\}$.
 - We may prove $sp(c, P) \Rightarrow Q$ instead.

Verification is reduced to the calculation of strongest postconditions.

Strongest Postconditions



The strongest postcondition of each program construct.

```
\begin{array}{l} \operatorname{sp}(\operatorname{\mathbf{skip}},P) = P \\ \operatorname{sp}(\operatorname{\mathbf{abort}},P) = \operatorname{\mathsf{false}} \\ \operatorname{sp}(x := e,P) = \exists x_0 : P[x_0/x] \land x = e[x_0/x] \\ \operatorname{sp}(c_1;c_2,P) = \operatorname{\mathit{sp}}(c_2,\operatorname{\mathit{sp}}(c_1,P)) \\ \operatorname{sp}(\operatorname{\mathbf{if}} b \operatorname{\mathbf{then}} c_1 \operatorname{\mathbf{else}} c_2,P) \Leftrightarrow \operatorname{sp}(c_1,P \land b) \lor \operatorname{sp}(c_2,P \land \neg b) \\ \operatorname{sp}(\operatorname{\mathbf{if}} b \operatorname{\mathbf{then}} c,P) = \operatorname{sp}(c,P \land b) \lor (P \land \neg b) \\ \operatorname{sp}(\operatorname{\mathbf{while}} b \operatorname{\mathbf{do}} c,P) = \dots \end{array}
```

Forward reasoning as a (less-known) alternative to backward-reasoning.

Hoare Calculus and Predicate Transformers



In practice, often a combination of the calculi is applied.

$$\{P\}\ c_1$$
; while b do c; $c_2\ \{Q\}$

- Assume c_1 and c_2 do not contain loop commands.
- It suffices to prove

$$\{sp(P, c_1)\}\$$
while $b\$ do $c\ \{wp(c_2, Q)\}$

Predicate transformers are applied to reduce the verification of a program to the Hoare-style verification of loops.

Weakest Liberal Preconditions for Loops



Why not apply predicate transformers to loops?

wp(loop,
$$Q$$
) = true
wp(while b do c , Q) = $L_0(Q) \wedge L_1(Q) \wedge L_2(Q) \wedge ...$

$$L_0(Q) = \text{true}$$

 $L_{i+1}(Q) = (\neg b \Rightarrow Q) \land (b \Rightarrow \text{wp}(c, L_i(Q)))$

- Interpretation
 - Weakest precondition that ensures that loops stops in a state satisfying Q, unless it aborts or runs forever.
- Infinite sequence of predicates $L_i(Q)$:
 - Weakest precondition that ensures that after less than *i* iterations the state satisfies *Q*, unless the loop aborts or does not yet terminate.
- Alternative view: $L_i(Q) = wp(if_i, Q)$ $if_0 = loop$ $if_{i+1} = if b then (c; if_i)$

Example



```
wp(while i < n do i := i + 1, Q)
L_0(Q) = \text{true}
L_1(Q) = (i \not< n \Rightarrow Q) \land (i < n \Rightarrow wp(i := i + 1, true))
           \Leftrightarrow (i \not< n \Rightarrow Q) \land (i < n \Rightarrow \text{true})
           \Leftrightarrow (i \not< n \Rightarrow Q)
L_2(Q) = (i \not< n \Rightarrow Q) \land (i < n \Rightarrow wp(i := i + 1, i \not< n \Rightarrow Q))
           \Leftrightarrow (i \not< n \Rightarrow Q) \land
                       (i < n \Rightarrow (i+1 \not< n \Rightarrow O[i+1/i]))
L_3(Q) = (i \not< n \Rightarrow Q) \land (i < n \Rightarrow wp(i := i + 1,
                       (i \not< n \Rightarrow Q) \land (i < n \Rightarrow (i+1 \not< n \Rightarrow Q[i+1/i])))
           \Leftrightarrow (i \not< n \Rightarrow Q) \land
                       (i < n \Rightarrow ((i+1 \not< n \Rightarrow Q[i+1/i]) \land
                                 (i+1 < n \Rightarrow (i+2 \not< n \Rightarrow Q[i+2/i])))
```

Weakest Liberal Preconditions for Loops



- Sequence $L_i(Q)$ is monotonically increasing in strength:
 - $\forall i \in \mathbb{N} : L_{i+1}(Q) \Rightarrow L_i(Q).$
- The weakest precondition is the "lowest upper bound":
 - $\forall i \in \mathbb{N} : wp(\mathbf{while} \ b \ \mathbf{do} \ c, Q) \Rightarrow L_i(Q).$
 - $\forall P : (\forall i \in \mathbb{N} : P \Rightarrow L_i(Q)) \Rightarrow (P \Rightarrow wp(\mathbf{while} \ b \ \mathbf{do} \ c, Q)).$
- We can only compute weaker approximation $L_i(Q)$.
 - wp(while *b* do c, Q) $\Rightarrow L_i(Q)$.
- We want to prove $\{P\}$ while b do c $\{Q\}$.
 - This is equivalent to proving $P \Rightarrow wp(\mathbf{while}\ b\ \mathbf{do}\ c, Q)$.
 - Thus $P \Rightarrow L_i(Q)$ must hold as well.
- If we can prove $\neg(P \Rightarrow L_i(Q)), \ldots$
 - P while b do c Q does not hold.
 - If we fail, we may try the easier proof $\neg (P \Rightarrow L_{i+1}(Q))$.

Falsification is possible by use of approximation L_i , but verification is not.



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A Constructive Definition of Arrays



```
% constructive array definition
                                    % the array operations
                                    length: ARR -> INDEX =
newcontext "arrays2";
                                      LAMBDA(a:ARR): a.0;
% the types
                                    new: TNDEX -> ARR =
INDEX: TYPE = NAT;
                                      LAMBDA(n:INDEX): (n, any);
ELEM: TYPE;
                                    put: (ARR, INDEX, ELEM) -> ARR =
ARR: TYPE =
                                     LAMBDA(a:ARR, i:INDEX, e:ELEM):
  [INDEX, ARRAY INDEX OF ELEM];
                                       IF i < length(a)</pre>
                                         THEN (length(a),
% error constants
                                               content(a) WITH [i]:=e)
any: ARRAY INDEX OF ELEM;
                                         ELSE anyarray
anyelem: ELEM;
                                       ENDIF;
anyarray: ARR;
                                    get: (ARR, INDEX) -> ELEM =
                                      LAMBDA(a:ARR, i:INDEX):
% a selector operation
                                        IF i < length(a)</pre>
                                          THEN content(a)[i]
content:
  ARR -> (ARRAY INDEX OF ELEM) =
                                          ELSE anyelem ENDIF;
  LAMBDA(a:ARR): a.1;
```

Proof of Fundamental Array Properties



```
% the classical array axioms as formulas to be proved
length1: FORMULA
  FORALL(n:INDEX): length(new(n)) = n;
length2: FORMULA
  FORALL(a:ARR, i:INDEX, e:ELEM):
    i < length(a) => length(put(a, i, e)) = length(a);
get1: FORMULA
  FORALL(a:ARR, i:INDEX, e:ELEM):
    i < length(a) \Rightarrow get(put(a, i, e), i) = e;
get2: FORMULA
                                          [adu]: expand length, get, put, content
  FORALL(a:ARR, i, j:INDEX, e:ELEM):
                                            [c3b]: scatter
    i < length(a) AND j < length(a) AND
                                              [qid]: proved (CVCL)
    i /= j =>
      get(put(a, i, e), j) = get(a, j);
```

Proof of a Higher-Level Array Property



```
% extensionality on low-level arrays
extensionality: AXIOM
  FORALL(a, b: ARRAY INDEX OF ELEM):
    a=b <=> (FORALL(i:INDEX):a[i]=b[i]);
% unassigned parts hold identical values
unassigned: AXIOM
                                         [adt]: expand length, get, content
  FORALL(a:ARR, i:INT):
                                           [cw2]: scatter
    (i >= length(a)) => content(a)[i
                                             [qey]: proved (CVCL)
                                             frevl: assume b 0.1 = a \cdot 0.1
                                               [zpt]: proved (CVCL)
                                               [1pt]: instantiate a 0.1, b 0.1 in 1fm
% extensionality on arrays to be pro-
                                                 [y51]: scatter
equality: FORMULA
                                                   [ku2]: auto
  FORALL(a:ARR, b:ARR): a = b <=>
                                                     [iub]: proved (CVCL)
    length(a) = length(b) AND
    (FORALL(i:INDEX): i < length(a) => get(a,i) = get(b,i));
```

A Program Verification



Verification of the following Hoare triple:

Find the smallest index r of an occurrence of value x in array a (r = -1, if x does not occur in a).

The Verification Conditions



```
A:\Leftrightarrow Input \Rightarrow Invariant
B_1 : \Leftrightarrow Invariant \land i < n \land r = -1 \land a[i] = x \Rightarrow Invariant[i/r]
B_2 : \Leftrightarrow Invariant \land i < n \land r = -1 \land a[i] \neq x \Rightarrow Invariant[i + 1/i]
C :\Leftrightarrow Invariant \land \neg (i < n \land r = -1) \Rightarrow Output
Input : \Leftrightarrow olda = a \land oldx = x \land n = length(a) \land i = 0 \land r = -1
Output :\Leftrightarrow a = olda \land x = oldx \land
   ((r = -1 \land \forall i : 0 < i < length(a) \Rightarrow a[i] \neq x) \lor
     (0 < r < length(a) \land a[r] = x \land \forall i : 0 \le i < r \Rightarrow a[i] \ne x))
Invariant :\Leftrightarrow olda = a \land oldx = x \land n = length(a) \land
   0 < i < n \land \forall j : 0 < j < i \Rightarrow a[j] \neq x \land
   (r = -1 \lor (r = i \land i < n \land a[r] = x))
```

The verification conditions A, B_1, B_2, C have to be proved.

The Verification Conditions



```
Input: BOOLEAN = olda = a AND oldx = x AND
newcontext
  "linsearch":
                        n = length(a) AND i = 0 AND r = -1;
% declaration
                      Output: BOOLEAN = a = olda AND
                        ((r = -1 AND)
% of arrays
                            (FORALL(j:NAT): j < length(a) =>
. . .
                               get(a,j) /= x)) OR
                         (0 \le r \text{ AND } r \le length(a) \text{ AND } get(a,r) = x \text{ AND}
a: ARR;
olda: ARR;
                            (FORALL(j:NAT):
x: ELEM;
                              j < r => get(a,j) /= x)));
oldx: ELEM;
i: NAT;
                      Invariant: (ARR, ELEM, NAT, NAT, INT) -> BOOLEAN =
n: NAT:
                        LAMBDA(a: ARR, x: ELEM, i: NAT, n: NAT, r: INT):
r: INT;
                          olda = a AND oldx = x AND
                          n = length(a) AND i \le n AND
                          (FORALL(j:NAT): j < i \Rightarrow get(a,j) /= x) AND
                          (r = -1 \text{ OR } (r = i \text{ AND } i < n \text{ AND } get(a,r) = x));
```

The Verification Conditions (Contd)



```
. . .
A · FORMIII.A
  Input => Invariant(a, x, i, n, r);
B1: FORMULA
  Invariant(a, x, i, n, r) AND i < n AND r = -1 AND get(a,i) = x
    => Invariant(a,x,i,n,i);
B2: FORMULA
  Invariant(a, x, i, n, r) AND i < n AND r = -1 AND get(a,i) /= x
    => Invariant(a,x,i+1,n,r);
C: FORMULA
  Invariant(a, x, i, n, r) AND NOT(i < n AND r = -1)
    => Output;
```

The Proofs



```
Α:
        [bca]: expand Input, Invariant
                                           B1:
                                                   [p1b]: expand Invariant
          [fuo]: scatter
                                                     [lf6]: proved (CVCL)
            [bxg]: proved (CVCL)
        (2 user actions)
                                                   (1 user action)
B2:
        [q1b]: expand Invariant in 6kv
                                                   [dca]: expand Invariant, Output in zfg
                                                     [tvv]: scatter
          [slx]: scatter
                                                       [dcu]: auto
             [a1y]: auto
                                                         [t4c]: proved (CVCL)
               [cch]: proved (CVCL)
                                                       [ecu]: split pkg
             [b1y]: proved (CVCL)
                                                         [kel]: proved (CVCL)
             [c1y]: proved (CVCL)
                                                         [lel]: scatter
             [d1y]: proved (CVCL)
                                                           [lvn]: auto
             [e1y]: proved (CVCL)
                                                             [lap]: proved (CVCL)
                                                       [fcu]: auto
                                                         [blt]: proved (CVCL)
                                                       [qcu]: proved (CVCL)
        (3 user actions)
                                                   (6 user actions)
```



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Termination



Hoare rules for loop and while are replaced as follows:

- New interpretation of $\{P\}$ c $\{Q\}$.
 - If execution of c starts in a state where P holds, then execution terminates in a state where Q holds, unless it aborts.
 - Non-termination is ruled out, abortion not (yet).
 - The **loop** command thus does not satisfy total correctness.
- \blacksquare Termination term t (type-checked to denote an integer).
 - Becomes smaller by every iteration of the loop.
 - But does not become negative.
 - Consequently, the loop must eventually terminate.

The initial value of t limits the number of loop iterations.

Any well-founded ordering may be used for the domain of t.



$$I :\Leftrightarrow s = \sum_{j=1}^{i-1} j \wedge 1 \le i \le n+1$$

$$(n \ge 0 \wedge i = 1 \wedge s = 0) \Rightarrow I \quad I \Rightarrow n-i+1 \ge 0$$

$$\{I \wedge i \le n \wedge n-i+1 = N\} \ s := s+i; i := i+1 \ \{I \wedge n-i+1 < N\}$$

$$(I \wedge i \le n) \Rightarrow s = \sum_{j=1}^{n} j$$

$$\{n \ge 0 \wedge i = 1 \wedge s = 0\} \ \text{while} \ i \le n \ \text{do} \ (s := s+i; i := i+1) \ \{s = \sum_{j=1}^{n} j\}$$

In practice, termination is easy to show (compared to partial correctness).

Weakest Preconditions for Loops



$$wp(\mathbf{loop}, Q) = \mathbf{false}$$

 $wp(\mathbf{while} \ b \ \mathbf{do} \ c, Q) = L_0(Q) \lor L_1(Q) \lor L_2(Q) \lor \dots$

$$L_0(Q) =$$
false $L_{i+1}(Q) = (\neg b \Rightarrow Q) \land (b \Rightarrow wp(c, L_i(Q)))$

- New interpretation
 - Weakest precondition that ensures that the loop terminates in a state in which Q holds, unless it aborts.
- New interpretation of $L_i(Q)$
 - Weakest precondition that ensures that the loop terminates after less than *i* iterations in a state in which *Q* holds, unless it aborts.
- Preserves property: $\{P\}$ c $\{Q\}$ iff $(P \Rightarrow wp(c, Q))$
 - Now for total correctness interpretation of Hoare calculus.
- Preserves alternative view: $L_i(Q) \Leftrightarrow wp(if_i, Q)$ $if_0 = \mathbf{loop}$ $if_{i+1} = \mathbf{if} \ b \ \mathbf{then} \ (c; if_i)$



```
wp(while i < n do i := i + 1, Q)
L_0(Q) = \text{false}
L_1(Q) = (i \leqslant n \Rightarrow Q) \land (i \leqslant n \Rightarrow wp(i := i + 1, L_0(Q)))
           \Leftrightarrow (i \not< n \Rightarrow Q) \land (i < n \Rightarrow \text{ false})
           \Leftrightarrow i \not< n \land Q
L_2(Q) = (i \not< n \Rightarrow Q) \land (i < n \Rightarrow wp(i := i + 1, L_1(Q)))
           \Leftrightarrow (i \not< n \Rightarrow Q) \land
                     i < n \Rightarrow (i + 1 \not< n \land Q[i + 1/i])
L_3(Q) = (i \not< n \Rightarrow Q) \land (i < n \Rightarrow wp(i := i + 1, L_2(Q)))
           \Leftrightarrow (i \lessdot n \Rightarrow Q) \land
                     (i < n \Rightarrow ((i + 1 \not< n \Rightarrow Q[i + 1/i]) \land
                              (i+1 < n \Rightarrow (i+2 \not< n \land Q[i+2/i])))
```

Weakest Preconditions for Loops



- Sequence $L_i(Q)$ is now monotonically decreasing in strength:
 - $\forall i \in \mathbb{N} : L_i(Q) \Rightarrow L_{i+1}(Q).$
- The weakest precondition is the "greatest lower bound":
 - $\forall i \in \mathbb{N} : L_i(Q) \Rightarrow \text{wp(while } b \text{ do } c, Q).$
 - $\forall P : (\forall i \in \mathbb{N} : L_i(Q) \Rightarrow P) \Rightarrow (\mathsf{wp}(\mathsf{while}\ b\ \mathsf{do}\ c, Q) \Rightarrow P).$
- We can only compute a stronger approximation $L_i(Q)$.
 - $L_i(Q) \Rightarrow wp(\mathbf{while}\ b\ \mathbf{do}\ c, Q)$.
- We want to prove $\{P\}$ c $\{Q\}$.
 - It suffices to prove $P \Rightarrow wp(\mathbf{while}\ b\ \mathbf{do}\ c, Q)$.
 - It thus also suffices to prove $P \Rightarrow L_i(Q)$.
 - If proof fails, we may try the easier proof $P \Rightarrow L_{i+1}(Q)$

However, verifications are typically not successful with any finite approximation of the weakest precondition.



- 1. The Hoare Calculus
- 2. Predicate Transformers
- 3. Proving Verification Conditions
- 4. Termination
- 5. Abortion
- 6. Procedures

Abortion



New rules to prevent abortion.

- New interpretation of $\{P\}$ c $\{Q\}$.
 - If execution of c starts in a state, in which property P holds, then it does not abort and eventually terminates in a state in which Q holds.
- Sources of abortion.
 - Division by zero.
 - Index out of bounds exception.

D(e) makes sure that every subexpression of e is well defined.

Definedness of Expressions



```
D(0) = \text{true}.
D(1) = \text{true}.
D(x) = \text{true}.
D(a[i]) = D(i) \land 0 \le i < \text{length}(a).
D(e_1 + e_2) = D(e_1) \wedge D(e_2).
D(e_1 * e_2) = D(e_1) \wedge D(e_2).
D(e_1/e_2) = D(e_1) \wedge D(e_2) \wedge e_2 \neq 0.
D(true) = true.
D(false) = true.
D(\neg b) = D(b).
D(b_1 \wedge b_2) = D(b_1) \wedge D(b_2).
D(b_1 \vee b_2) = D(b_1) \wedge D(b_2).
D(e_1 < e_2) = D(e_1) \wedge D(e_2).
D(e_1 < e_2) = D(e_1) \wedge D(e_2).
D(e_1 > e_2) = D(e_1) \wedge D(e_2).
D(e_1 > e_2) = D(e_1) \wedge D(e_2).
```

Assumes that expressions have already been type-checked.

Abortion



Slight modification of existing rules.

$$\frac{P \Rightarrow D(b) \quad \{P \land b\} \ c_1 \ \{Q\} \quad \{P \land \neg b\} \ c_2 \ \{Q\}\}}{\{P\} \text{ if } b \text{ then } c_1 \text{ else } c_2 \ \{Q\}}$$

$$\frac{P \Rightarrow D(b) \quad \{P \land b\} \ c \ \{Q\} \quad (P \land \neg b) \Rightarrow Q}{\{P\} \text{ if } b \text{ then } c \ \{Q\}}$$

$$\frac{I \Rightarrow (t \ge 0 \land D(b)) \quad \{I \land b \land t = N\} \ c \ \{I \land t < N\}}{\{I\} \text{ while } b \text{ do } c \ \{I \land \neg b\}}$$

Expressions must be defined in any context.

Abortion



Similar modifications of weakest preconditions.

$$\begin{aligned} &\operatorname{wp}(\mathbf{abort},Q) = \operatorname{false} \\ &\operatorname{wp}(x := e,Q) = Q[e/x] \wedge D(e) \\ &\operatorname{wp}(\mathbf{if}\ b\ \mathbf{then}\ c_1\ \mathbf{else}\ c_2,Q) = \\ &D(b) \wedge (b \Rightarrow \operatorname{wp}(c_1,Q)) \wedge (\neg b \Rightarrow \operatorname{wp}(c_2,Q)) \\ &\operatorname{wp}(\mathbf{if}\ b\ \mathbf{then}\ c,Q) = D(b) \wedge (b \Rightarrow \operatorname{wp}(c,Q)) \wedge (\neg b \Rightarrow Q) \\ &\operatorname{wp}(\mathbf{while}\ b\ \mathbf{do}\ c,Q) = (L_0(Q) \vee L_1(Q) \vee L_2(Q) \vee \ldots) \end{aligned}$$

wp(c, Q) now makes sure that the execution of c does not abort but eventually terminates in a state in which Q holds.



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Procedure Specifications



```
global g;
requires Pre;
ensures Post;
o := p(i) \{ c \}
```

- \blacksquare Specification of a procedure p implemented by a command c.
 - Input parameter i, output parameter o, global variable g.
 - Command c may read/write i, o, and g.
 - Precondition Pre (may refer to i, g).
 - Postcondition *Post* (may refer to i, o, g, g_0).
 - g_0 denotes the value of g before the execution of p.
- Proof obligation

$$\{Pre \wedge i_0 = i \wedge g_0 = g\} \ c \ \{Post[i_0/i]\}$$

Proof of the correctness of the implementation of a procedure with respect to its specification.



Procedure specification:

```
global g requires g \ge 0 \land i > 0 ensures g_0 = g \cdot i + o \land 0 \le o < i o := p(i)  { o := g\%i; g := g/i }
```

■ Proof obligation:

$$\{g \ge 0 \land i > 0 \land i_0 = i \land g_0 = g\}$$

 $o := g\%i; g := g/i$
 $\{g_0 = g \cdot i_0 + o \land 0 \le o < i_0\}$

A procedure that divides g by i and returns the remainder.

Procedure Calls



A call of p provides actual input argument e and output variable x.

$$x := p(e)$$

Similar to assignment statement; we thus first give an alternative (equivalent) version of the assignment rule.

Original:

$$\begin{cases}
D(e) \land Q[e/x] \\
x := e \\
\{Q\}
\end{cases}$$

Alternative:

$$\{D(e) \land \forall x' : x' = e \Rightarrow Q[x'/x]\}$$

$$x := e$$

$$\{Q\}$$

The new value of x is given name x' in the precondition.

Procedure Calls



From this, we can derive a rule for the correctness of procedure calls.

$$\begin{cases} D(e) \land Pre[e/i] \land \\ \forall x', g' : Post[e/i, x'/o, g/g_0, g'/g] \Rightarrow Q[x'/x, g'/g] \rbrace \\ x := p(e) \\ \{Q\} \end{cases}$$

- Pre[e/i] refers to the values of the actual argument e (rather than to the formal parameter i).
- \mathbf{z}' and \mathbf{g}' denote the values of the vars x and g after the call.
- Post[...] refers to the argument values before and after the call.
- Q[x'/x, g'/g] refers to the argument values after the call.

Modular reasoning: rule only relies on the specification of p, not on its implementation.

Corresponding Predicate Transformers



```
 \begin{aligned} & \mathsf{wp}(x = p(e), Q) = \\ & D(e) \land Pre[e/i] \land \\ & \forall x', g' : \\ & Post[e/i, x'/o, g/g_0, g'/g] \Rightarrow Q[x'/x, g'/g] \\ & \mathsf{sp}(P, x = p(e)) = \\ & \exists x_0, g_0 : \\ & P[x_0/y, g_0/g] \land \\ & (Pre[e[x_0/x, g_0/g]/i, g_0/g] \Rightarrow Post[e[x_0/x, g_0/g]/i, x/o]) \end{aligned}
```

Explicit naming of old/new values required.



Procedure specification:

global
$$g$$
 requires $g \ge 0 \land i > 0$ ensures $g_0 = g \cdot i + o \land 0 \le o < i$ $o = p(i) \ \{ o := g\%i; \ g := g/i \ \}$

Procedure call:

$$\{g \ge 0 \land g = N \land b \ge 0\}$$

$$x = p(b+1)$$

$$\{g \cdot (b+1) \le N < (g+1) \cdot (b+1)\}$$

■ To be proved:

$$g \ge 0 \land g = N \land b \ge 0 \Rightarrow \\ D(b+1) \land g \ge 0 \land b+1 > 0 \land \\ \forall x', g' : \\ g = g' \cdot (b+1) + x' \land 0 \le x' < b+1 \Rightarrow \\ g' \cdot (b+1) \le N < (g'+1) \cdot (b+1)$$