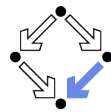


Modeling Concurrent Systems

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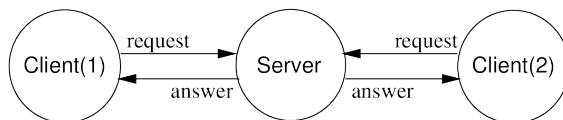
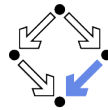
1. A Client/Server System

2. Modeling Concurrent Systems

3. A Model of the Client/Server System

4. Summary

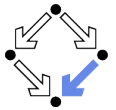
A Client/Server System



- System of one server and two clients.
 - Three **concurrently** executing system components.
- Server manages a resource.
 - An object that only one system component may use at any time.
- Clients request resource and, having received an answer, use it.
 - Server ensures that not both clients use resource simultaneously.
 - Server eventually answers every request.

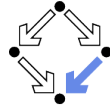
Set of system requirements.

System Implementation



```
Server:
  local given, waiting, sender
begin
  given := 0; waiting := 0
  loop
    sender := receiveRequest()
    if sender = given then
      if waiting = 0 then
        given := 0
      else
        given := waiting; waiting := 0
      end if
      sendAnswer(given)
    end if
    elsif given = 0 then
      given := sender
      sendAnswer(given)
    else
      waiting := sender
    end if
  end loop
end Server

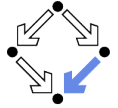
Client(id):
  param id
begin
  loop
    ...
    sendRequest()
    receiveAnswer()
    ... // critical region
    sendRequest()
  end loop
end Client
```



Desired System Properties

- Property: **mutual exclusion**.
 - At no time, both clients are in critical region.
 - Critical region: program region after receiving resource from server and before returning resource to server.
 - The system shall only reach states, in which mutual exclusion holds.
- Property: **no starvation**.
 - Always when a client requests the resource, it eventually receives it.
 - Always when the system reaches a state, in which a client has requested a resource, it shall later reach a state, in which the client receives the resource.
- Problem: each system component executes its own program.
 - Multiple program states exist at each moment in time.
 - Total system state is **combination of individual program states**.
 - Not easy to see which system states are possible or inevitable.

How can we verify that the system has the desired properties?

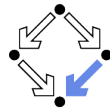


1. A Client/Server System

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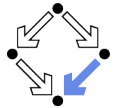


System States

At each moment in time, a system is in a particular state.

- A **state** $s : Var \rightarrow Val$
 - A state s is a mapping of every system variable x to its value $s(x)$.
 - Typical notation: $s = [x = 0, y = 1, \dots] = [0, 1, \dots]$.
 - Var ... the set of system variables
 - Program variables, program counters, ...
 - Val ... the set of variable values.
- The **state space** $State = \{s \mid s : Var \rightarrow Val\}$
 - The state space is the set of possible states.
 - The system variables can be viewed as the coordinates of this space.
 - The state space may (or may not) be finite.
 - If $|Var| = n$ and $|Val| = m$, then $|State| = m^n$.
 - A word of $\log_2 m^n$ bits can represent every state.

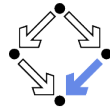
A system execution can be described by a path $s_0 \rightarrow s_1 \rightarrow s_2 \rightarrow \dots$ in the state space.



Deterministic Systems

In a sequential system, each state typically determines its successor state.

- The system is **deterministic**.
 - We have a (possibly not total) **transition function** F on states.
 - $s_1 = F(s_0)$ means “ s_1 is the successor of s_0 ”.
- Given an initial state s_0 , the execution is thus determined.
 - $s_0 \rightarrow s_1 = F(s_0) \rightarrow s_2 = F(s_1) \rightarrow \dots$
- A **deterministic system (model)** is a pair $\langle I, F \rangle$.
 - A set of initial states $I \subseteq State$
 - **Initial state condition** $I(s) :\Leftrightarrow s \in I$
 - A transition function $F : State \xrightarrow{\text{partial}} State$.
- A **run** of a deterministic system $\langle I, F \rangle$ is a (finite or infinite) sequence $s_0 \rightarrow s_1 \rightarrow \dots$ of states such that
 - $s_0 \in I$ (respectively $I(s_0)$).
 - $s_{i+1} = F(s_i)$ (for all sequence indices i)
 - If s ends in a state s_n , then F is not defined on s_n .

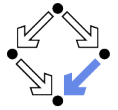


Nondeterministic Systems

In a concurrent system, each component may change its local state, thus the successor state is not uniquely determined.

- The system is **nondeterministic**.
 - We have a **transition relation** R on states.
 - $R(s_0, s_1)$ means “ s_1 is a (possible) successor of s_0 ”.
- Given an initial state s_0 , the execution is not uniquely determined.
 - Both $s_0 \rightarrow s_1 \rightarrow \dots$ and $s_0 \rightarrow s'_1 \rightarrow \dots$ are possible.
- A **non-deterministic system (model)** is a pair $\langle I, R \rangle$.
 - A set of initial states (initial state condition) $I \subseteq \text{State}$.
 - A transition relation $R \subseteq \text{State} \times \text{State}$.
- A **run** s of a nondeterministic system $\langle I, R \rangle$ is a (finite or infinite) sequence $s_0 \rightarrow s_1 \rightarrow s_2 \dots$ of states such that
 - $s_0 \in I$ (respectively $I(s_0)$).
 - $R(s_i, s_{i+1})$ (for all sequence indices i).
 - If s ends in a state s_n , then there is no state t such that $R(s_n, t)$.

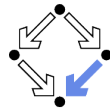
Derived Notions



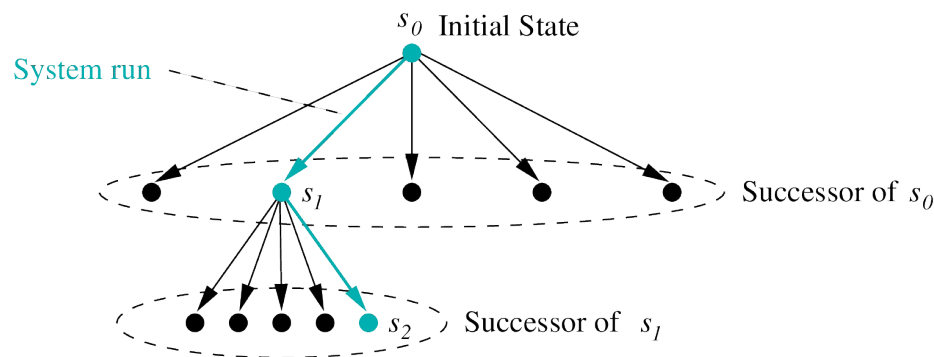
- Successor and predecessor:
 - State t is a **(direct) successor** of state s , if $R(s, t)$.
 - State s is then a **predecessor** of t .
 - A finite run $s_0 \rightarrow \dots \rightarrow s_n$ ends in a state which has no successor.
- Reachability:
 - A state t is **reachable**, if there exists some run $s_0 \rightarrow s_1 \rightarrow s_2 \rightarrow \dots$ such that $t = s_i$ (for some i).
 - A state t is **unreachable**, if it is not reachable.

Not all states are reachable (typically most are unreachable).

Reachability Graph



The transitions of a system can be visualized by a graph.



The nodes of the graph are the reachable states of the system.

Examples

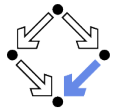


Fig. 1.1. A model of a watch

of A_{c3} correspond to the possible counter values. Its transitions reflect the possible actions on the counter. In this example we restrict our operations to increments (inc) and decrements (dec).

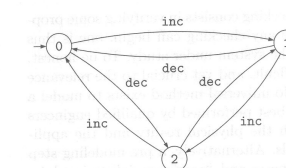
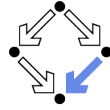
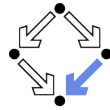


Fig. 1.2. A_{c3} : a modulo 3 counter



Examples

- A deterministic system $W = (I_W, F_W)$ ("watch").
 - $State := \mathbb{N}_{24} \times \mathbb{N}_{60}$.
 - $\mathbb{N}_n := \{i \in \mathbb{N} : i < n\}$.
 - $I_W(h, m) :\Leftrightarrow h = 0 \wedge m = 0$.
 - $I_W := \{(h, m) : h = 0 \wedge m = 0\} = \{(0, 0)\}$.
 - $F_W(h, m) :=$
 - if $m < 59$ then $\langle h, m + 1 \rangle$
 - else if $h < 23$ then $\langle h + 1, 0 \rangle$
 - else $\langle 0, 0 \rangle$.
- A nondeterministic system $C = (I_C, R_C)$ (modulo 3 "counter").
 - $State := \mathbb{N}_3$.
 - $I_C(i) :\Leftrightarrow i = 0$.
 - $R_C(i, i') :\Leftrightarrow inc(i, i') \vee dec(i, i')$.
 - $inc(i, i') :\Leftrightarrow$ if $i < 2$ then $i' = i + 1$ else $i' = 0$.
 - $dec(i, i') :\Leftrightarrow$ if $i > 0$ then $i' = i - 1$ else $i' = 2$.



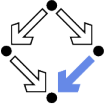
Initial States of Composed System

What are the initial states I of the composed system?

- **Set** $I := I_0 \times \dots \times I_{n-1}$.
 - I_i is the set of initial states of component i .
 - Set of initial states is Cartesian product of the sets of initial states of the individual components.
- **Predicate** $I(s_0, \dots, s_{n-1}) :\Leftrightarrow I_0(s_0) \wedge \dots \wedge I_{n-1}(s_{n-1})$.
 - I_i is the initial state condition of component i .
 - Initial state condition is conjunction of the initial state conditions of the components **on the corresponding projection** of the state.

Size of initial state set is the product of the sizes of the initial state sets of the individual components.

Composing Systems



Compose n components S_i to a concurrent system S .

- **State space** $State := State_0 \times \dots \times State_{n-1}$.
 - $State_i$ is the state space of component i .
 - State space is Cartesian product of component state spaces.
 - Size of state space is product of the sizes of the component spaces.
- **Example:** three counters with state spaces $\mathbb{N}_2$ and $\mathbb{N}_3$ and $\mathbb{N}_4$.

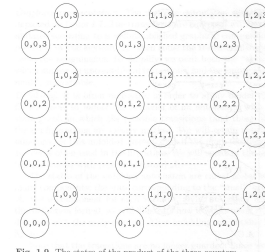
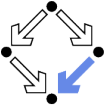


Fig. 1.9. The states of the product of the three counters

B.Berard et al: "Systems and Software Verification", 2001.



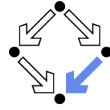
Transitions of Composed System

Which transitions can the composed system perform?

- **Synchronized composition.**
 - At each step, every component **must** perform a transition.
 - R_i is the transition relation of component i .

$$R((s_0, \dots, s_{n-1}), (s'_0, \dots, s'_{n-1})) :\Leftrightarrow R_0(s_0, s'_0) \wedge \dots \wedge R_{n-1}(s_{n-1}, s'_{n-1}).$$
- **Asynchronous composition.**
 - At each moment, every component **may** perform a transition.
 - At least one component performs a transition.
 - Multiple simultaneous transitions are possible
 - With n components, $2^n - 1$ possibilities of (combined) transitions.

$$R((s_0, \dots, s_{n-1}), (s'_0, \dots, s'_{n-1})) :\Leftrightarrow (R_0(s_0, s'_0) \wedge \dots \wedge s_{n-1} = s'_{n-1}) \vee \dots \vee (s_0 = s'_0 \wedge \dots \wedge R_{n-1}(s_{n-1}, s'_{n-1})) \vee \dots \vee (R_0(s_0, s'_0) \wedge \dots \wedge R_{n-1}(s_{n-1}, s'_{n-1})).$$



Example

System of three counters with state space $\mathbb{N}_2$ each.

- Synchronous composition:

$$[0, 0, 0] \Leftrightarrow [1, 1, 1]$$

- Asynchronous composition:

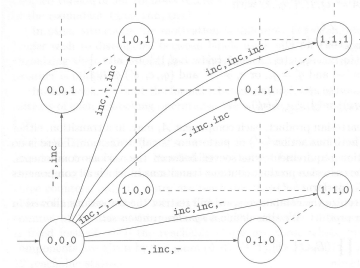
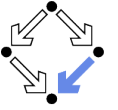


Fig. 1.10. A few transitions of the product of the three counters

B.Berard et al: "Systems and Software Verification", 2001.

Interleaving Execution



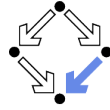
Simplified view of asynchronous execution.

- At each moment, only **one** component performs a transition.
 - Do not allow simultaneous transition $t_i|t_j$ of two components i and j .
 - Transition sequences $t_i; t_j$ and $t_j; t_i$ are possible.
 - All possible **interleavings** of component transitions are considered.
 - Nondeterminism is used to simulate concurrency.
 - Essentially no change of system properties.
- With n components, only n possibilities of a transition.

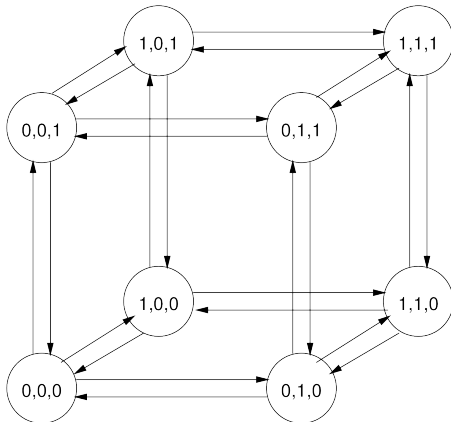
$$R(\langle s_0, s_1, \dots, s_{n-1} \rangle, \langle s'_0, s'_1, \dots, s'_{n-1} \rangle) :\Leftrightarrow \\ (R_0(s_0, s'_0) \wedge s_1 = s'_1 \wedge \dots \wedge s_{n-1} = s'_{n-1}) \vee \\ (s_0 = s'_0 \wedge R_1(s_1, s'_1) \wedge \dots \wedge s_{n-1} = s'_{n-1}) \vee \\ \dots \\ (s_0 = s'_0 \wedge s_1 = s'_1 \wedge \dots \wedge R_{n-1}(s_{n-1}, s'_{n-1})).$$

Interleaving model (respectively a variant of it) suffices in practice.

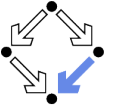
Example



System of three counters with state space $\mathbb{N}_2$ each.



Digital Circuits



Synchronous composition of hardware components.

- A **modulo 8 counter** $C = \langle I_C, R_C \rangle$.

$$\text{State} := \mathbb{N}_2 \times \mathbb{N}_2 \times \mathbb{N}_2.$$

$$I_C(v_0, v_1, v_2) :\Leftrightarrow v_0 = v_1 = v_2 = 0.$$

$$R_C(\langle v_0, v_1, v_2 \rangle, \langle v'_0, v'_1, v'_2 \rangle) :\Leftrightarrow \\ R_0(v_0, v'_0) \wedge \\ R_1(v_0, v_1, v'_1) \wedge \\ R_2(v_0, v_1, v_2, v'_2).$$

$$R_0(v_0, v'_0) :\Leftrightarrow v'_0 = \neg v_0.$$

$$R_1(v_0, v_1, v'_1) :\Leftrightarrow v'_1 = v_0 \oplus v_1.$$

$$R_2(v_0, v_1, v_2, v'_2) :\Leftrightarrow v'_2 = (v_0 \wedge v_1) \oplus v_2.$$

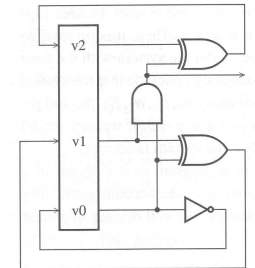
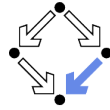


Figure 2.1
Synchronous modulo 8 counter.

Edmund Clarke et al: "Model Checking", 1999.

Concurrent Software



Asynchronous composition of software components with shared variables.

$P :: l_0 : \text{while true do}$ $||$ $Q :: l_1 : \text{while true do}$
 $NC_0 : \text{wait turn} = 0$ $NC_1 : \text{wait turn} = 1$
 $CR_0 : \text{turn} := 1$ $CR_1 : \text{turn} := 0$
 end end

- A mutual exclusion program $M = \langle I_M, R_M \rangle$.

State := $PC \times PC \times \mathbb{N}_2$. // shared variable

$I_M(p, q, \text{turn}) :\Leftrightarrow p = l_0 \wedge q = l_1$.

$R_M(\langle p, q, \text{turn} \rangle, \langle p', q', \text{turn}' \rangle) :\Leftrightarrow$

$(P(\langle p, \text{turn} \rangle, \langle p', \text{turn}' \rangle) \wedge q' = q) \vee (Q(\langle q, \text{turn} \rangle, \langle q', \text{turn}' \rangle) \wedge p' = p)$.

$P(\langle p, \text{turn} \rangle, \langle p', \text{turn}' \rangle) :\Leftrightarrow$

$(p = l_0 \wedge p' = NC_0 \wedge \text{turn}' = \text{turn}) \vee$

$(p = NC_0 \wedge p' = CR_0 \wedge \text{turn} = 0 \wedge \text{turn}' = \text{turn}) \vee$

$(p = CR_0 \wedge p' = l_0 \wedge \text{turn}' = 1)$.

$Q(\langle q, \text{turn} \rangle, \langle q', \text{turn}' \rangle) :\Leftrightarrow$

$(q = l_1 \wedge q' = NC_1 \wedge \text{turn}' = \text{turn}) \vee$

$(q = NC_1 \wedge q' = CR_1 \wedge \text{turn} = 1 \wedge \text{turn}' = \text{turn}) \vee$

$(q = CR_1 \wedge q' = l_1 \wedge \text{turn}' = 0)$.

Concurrent Software

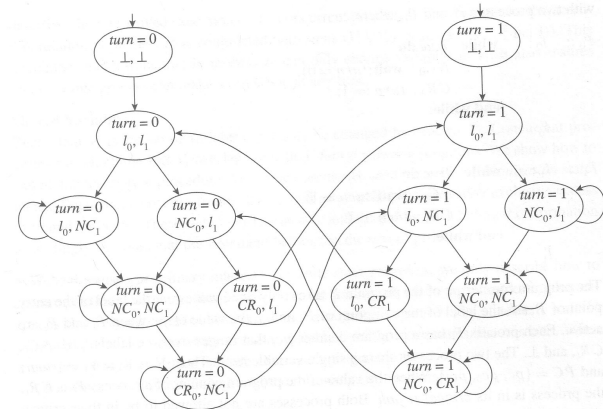
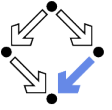
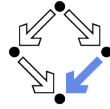


Figure 2.2
Reachable states of Kripke structure for mutual exclusion example.

Edmund Clarke et al: "Model Checking", 1999.

Model guarantees mutual exclusion.

Modeling Commands



Transition relations are typically described in a particular form.

- $R(s, s') :\Leftrightarrow P(s) \wedge s' = F(s)$.

- Guard condition P on state in which transition can be performed.

- If $P(s)$ holds, then there exists some s' such that $R(s, s')$.

- Transition function F that determines the successor of s .

- F is defined for all states for which $P(s)$ holds:

$F : \{s \in \text{State} : P(s)\} \rightarrow \text{State}$.

- Examples:

- Assignment: $l : x := e; m : \dots$

- $R(\langle pc, x, y \rangle, \langle pc', x', y' \rangle) :\Leftrightarrow pc = l \wedge (x' = e \wedge y' = y \wedge pc' = m)$.

- Wait statement: $l : \text{wait } P(x, y); m : \dots$

- $R(\langle pc, x, y \rangle, \langle pc', x', y' \rangle) :\Leftrightarrow$

$pc = l \wedge P(x, y) \wedge (x' = x \wedge y' = y \wedge pc' = m)$.

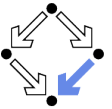
- Guarded assignment: $l : P(x, y) \rightarrow x := e; m : \dots$

- $R(\langle pc, x, y \rangle, \langle pc', x', y' \rangle) :\Leftrightarrow$

$pc = l \wedge P(x, y) \wedge (x' = e \wedge y' = y \wedge pc' = m)$.

Most programming language commands can be translated into this form.

Modelling Message Passing Systems



How to model an asynchronous system without shared variables where the components communicate/synchronize by exchanging messages?

- Given a label set $\text{Label} = \text{Int} \cup \text{Ext} \cup \overline{\text{Ext}}$.

- Disjoint sets Int and Ext of internal and external labels.

- "Anonymous" label $_ \in \text{Int}$.

- Complementary label set $\bar{L} := \{\bar{l} : l \in L\}$.

- A labeled system is a pair $\langle I, R \rangle$.

- Initial state condition $I \subseteq \text{State}$.

- Labeled transition relation $R \subseteq \text{Label} \times \text{State} \times \text{State}$.

- A run of a labeled system $\langle I, R \rangle$ is a (finite or infinite) sequence

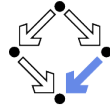
$s_0 \xrightarrow{l_0} s_1 \xrightarrow{l_1} \dots$ of states such that

- $s_0 \in I$.

- $R(l_i, s_i, s_{i+1})$ (for all sequence indices i).

- If s ends in a state s_n , there is no label l and state t s.t. $R(l, s_n, t)$.

Synchronization by Message Passing



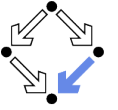
Compose a set of n labeled systems $\langle I_i, R_i \rangle$ to a system $\langle I, R \rangle$.

- **State space** $State := State_0 \times \dots \times State_{n-1}$.
- **Initial states** $I := I_0 \times \dots \times I_{n-1}$.
 - $I(s_0, \dots, s_{n-1}) :\Leftrightarrow I_0(s_0) \wedge \dots \wedge I_{n-1}(s_{n-1})$.
- **Transition relation**

$$\begin{aligned}
 R(I, \langle s_i \rangle_{i \in \mathbb{N}_n}, \langle s'_i \rangle_{i \in \mathbb{N}_n}) &\Leftrightarrow \\
 (I \in \text{Int} \wedge \exists i \in \mathbb{N}_n : & \\
 R_i(I, s_i, s'_i) \wedge \forall k \in \mathbb{N}_n \setminus \{i\} : s_k = s'_k) \vee & \\
 (I = _ \wedge \exists l \in \text{Ext}, i \in \mathbb{N}_n, j \in \mathbb{N}_n : & \\
 R_i(I, s_i, s'_i) \wedge R_j(I, s_j, s'_j) \wedge \forall k \in \mathbb{N}_n \setminus \{i, j\} : s_k = s'_k). &
 \end{aligned}$$

Either a component performs an internal transition or two components simultaneously perform an external transition with complementary labels.

Communication by Message Passing



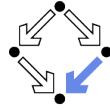
```

0 :: loop
  a0 : send(i)
  a1 : i := receive()
  a2 : i := i + 1
end

1 :: loop
  b0 : j := receive()
  b1 : j := j + 1
  b2 : send(j)
end
    
```

- Two labeled systems $\langle I_0, R_0 \rangle$ and $\langle I_1, R_1 \rangle$.
 $State_0 = State_1 = PC \times \mathbb{N}$, $Internal := \{A, B\}$, $External := \{M, N\}$.
 $I_0(p, i) :\Leftrightarrow p = a_0 \wedge i \in \mathbb{N}$; $I_1(q, j) :\Leftrightarrow q = b_0$.
 $R_0(I, \langle p, i \rangle, \langle p', i' \rangle) :\Leftrightarrow$
 $(I = \overline{M} \wedge p = a_0 \wedge p' = a_1 \wedge i' = i) \vee$
 $(I = N \wedge p = a_1 \wedge p' = a_2 \wedge i' = j) \vee$ // illegal!
 $(I = A \wedge p = a_2 \wedge p' = a_0 \wedge i' = i + 1)$.
 $R_1(I, \langle q, j \rangle, \langle q', j' \rangle) :\Leftrightarrow$
 $(I = M \wedge q = b_0 \wedge q' = b_1 \wedge j' = i) \vee$ // illegal!
 $(I = B \wedge q = b_1 \wedge q' = b_2 \wedge j' = j + 1) \vee$
 $(I = \overline{N} \wedge q = b_2 \wedge q' = b_0 \wedge j' = j)$.

Example (Continued)



Composition of $\langle I_0, R_0 \rangle$ and $\langle I_1, R_1 \rangle$ to $\langle I, R \rangle$.

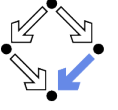
$$State = (PC \times \mathbb{N}) \times (PC \times \mathbb{N}).$$

$$I(p, i, q, j) :\Leftrightarrow p = a_0 \wedge i \in \mathbb{N} \wedge q = b_0.$$

$$\begin{aligned}
 R(I, \langle p, i, q, j \rangle, \langle p', i', q', j' \rangle) &\Leftrightarrow \\
 (I = A \wedge (p = a_2 \wedge p' = a_0 \wedge i' = i + 1) \wedge (q' = q \wedge j' = j)) \vee & \\
 (I = B \wedge (p' = p \wedge i' = i) \wedge (q = b_1 \wedge q' = b_2 \wedge j' = j + 1)) \vee & \\
 (I = _ \wedge (p = a_0 \wedge p' = a_1 \wedge i' = i) \wedge (q = b_0 \wedge q' = b_1 \wedge j' = i)) \vee & \\
 (I = _ \wedge (p = a_1 \wedge p' = a_2 \wedge i' = j) \wedge (q = b_2 \wedge q' = b_0 \wedge j' = j)). &
 \end{aligned}$$

Problem: state relation of each component refers to local variable of other component (variables are shared).

Example (Revised)



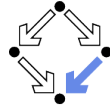
```

0 :: loop
  a0 : send(i)
  a1 : i := receive()
  a2 : i := i + 1
end

1 :: loop
  b0 : j := receive()
  b1 : j := j + 1
  b2 : send(j)
end
    
```

- Two labeled systems $\langle I_0, R_0 \rangle$ and $\langle I_1, R_1 \rangle$.
 $\dots$
 $External := \{M_k : k \in \mathbb{N}\} \cup \{N_k : k \in \mathbb{N}\}$.
 $R_0(I, \langle p, i \rangle, \langle p', i' \rangle) :\Leftrightarrow$
 $(I = \overline{M_i} \wedge p = a_0 \wedge p' = a_1 \wedge i' = i) \vee$
 $(\exists k \in \mathbb{N} : I = N_k \wedge p = a_1 \wedge p' = a_2 \wedge i' = k) \vee$
 $(I = A \wedge p = a_2 \wedge p' = a_0 \wedge i' = i + 1)$.
 $R_1(I, \langle q, j \rangle, \langle q', j' \rangle) :\Leftrightarrow$
 $(\exists k \in \mathbb{N} : I = M_k \wedge q = b_0 \wedge q' = b_1 \wedge j' = k) \vee$
 $(I = B \wedge q = b_1 \wedge q' = b_2 \wedge j' = j + 1) \vee$
 $(I = \overline{N_j} \wedge q = b_2 \wedge q' = b_0 \wedge j' = j)$.

Encode message value in label.



Example (Continued)

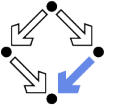
Composition of $\langle I_0, R_0 \rangle$ and $\langle I_1, R_1 \rangle$ to $\langle I, R \rangle$.

$$State = (PC \times \mathbb{N}) \times (PC \times \mathbb{N}).$$

$$I(p, i, q, j) :\Leftrightarrow p = a_0 \wedge i \in \mathbb{N} \wedge q = b_0.$$

$$\begin{aligned} R(I, \langle p, i, q, j \rangle, \langle p', i', q', j' \rangle) :\Leftrightarrow \\ & (I = A \wedge (p = a_2 \wedge p' = a_0 \wedge i' = i + 1) \wedge (q' = q \wedge j' = j)) \vee \\ & (I = B \wedge (p' = p \wedge i' = i) \wedge (q = b_1 \wedge q' = b_2 \wedge j' = j + 1)) \vee \\ & (I = _ \wedge \exists k \in \mathbb{N} : k = i \wedge \\ & \quad (p = a_0 \wedge p' = a_1 \wedge i' = i) \wedge (q = b_0 \wedge q' = b_1 \wedge j' = k)) \vee \\ & (I = _ \wedge \exists k \in \mathbb{N} : k = j \wedge \\ & \quad (p = a_1 \wedge p' = a_2 \wedge i' = k) \wedge (q = b_2 \wedge q' = b_0 \wedge j' = j)). \end{aligned}$$

Logically equivalent to previous definition of transition relation.

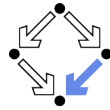


1. A Client/Server System

2. Modeling Concurrent Systems

3. A Model of the Client/Server System

4. Summary



The Client/Server System

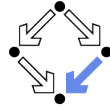
Asynchronous composition of three components $Client_1$, $Client_2$, $Server$.

- $Client_i$: $State := PC \times \mathbb{N}_2 \times \mathbb{N}_2$.
 - Three variables pc , $request$, $answer$.
 - pc represents the program counter.
 - $request$ is the buffer for outgoing requests.
 - Filled by client, when a request is to be sent to server.
 - $answer$ is the buffer for incoming answers.
 - Checked by client, when it waits for an answer from the server.
- $Server$: $State := (\mathbb{N}_3)^3 \times (\{1, 2\} \rightarrow \mathbb{N}_2)^2$.
 - Variables $given$, $waiting$, $sender$, $rbuffer$, $sbuffer$.
 - No program counter.
 - We use the value of $sender$ to check whether server waits for a request ($sender = 0$) or answers a request ($sender \neq 0$).
 - Variables $given$, $waiting$, $sender$ as in program.
 - $rbuffer(i)$ is the buffer for incoming requests from client i .
 - $sbuffer(i)$ is the buffer for outgoing answers to client i .

External Transitions

- $Ext := \{REQ_1, REQ_2, ANS_1, ANS_2\}$.
 - Transition labeled REQ_i transmits a request from client i to server.
 - Enabled when $request \neq 0$ in client i .
 - Effect in client i : $request' = 0$.
 - Effect in server: $rbuffer'(i) = 1$.
 - Transition labeled ANS_i transmits an answer from server to client i
 - Enabled when $sbuffer(i) \neq 0$.
 - Effect in server: $sbuffer'(i) = 0$.
 - Effect in client i : $answer' = 1$.

The external transitions correspond to system-level actions of the communication subsystem (rather than to the user-level actions of the client/server program).



The Client

Client system $C_i = \langle IC_i, RC_i \rangle$.

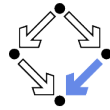
State := $PC \times \mathbb{N}_2 \times \mathbb{N}_2$.

Int := $\{R_i, S_i, C_i\}$.

$IC_i(pc, request, answer) : \Leftrightarrow$
 $pc = R \wedge request = 0 \wedge answer = 0$.
 $RC_i(I, \langle pc, request, answer \rangle, \langle pc', request', answer' \rangle) : \Leftrightarrow$
 $(I = R_i \wedge pc = R \wedge request = 0 \wedge$
 $pc' = S \wedge request' = 1 \wedge answer' = answer) \vee$
 $(I = S_i \wedge pc = S \wedge answer \neq 0 \wedge$
 $pc' = C \wedge request' = request \wedge answer' = 0) \vee$
 $(I = C_i \wedge pc = C \wedge request = 0 \wedge$
 $pc' = R \wedge request' = 1 \wedge answer' = answer) \vee$

 $(I = REQ_i \wedge request \neq 0 \wedge$
 $pc' = pc \wedge request' = 0 \wedge answer' = answer) \vee$
 $(I = ANS_i \wedge$
 $pc' = pc \wedge request' = request \wedge answer' = 1)$.

```
Client(ident):
  param ident
  begin
    loop
      ...
      R: sendRequest()
      S: receiveAnswer()
      C: // critical region
      ...
      sendRequest()
    endloop
  end Client
```



The Server (Contd)

```
Server:
  local given, waiting, sender
  begin
    given := 0; waiting := 0
    loop
      D: sender := receiveRequest()
      if sender = given then
        if waiting = 0 then
          F: given := 0
          else
            A1: given := waiting;
                waiting := 0
                sendAnswer(given)
            endif
          elsif given = 0 then
            A2: given := sender
                sendAnswer(given)
            else
              W: waiting := sender
            endif
          endloop
        end Server
```

...

$(I = F \wedge sender \neq 0 \wedge sender = given \wedge waiting = 0 \wedge$
 $given' = 0 \wedge sender' = 0 \wedge$
 $U(waiting, rbuffer, sbuffer)) \vee$

$(I = A1 \wedge sender \neq 0 \wedge sbuffer(waiting) = 0 \wedge$
 $sender = given \wedge waiting \neq 0 \wedge$
 $given' = waiting \wedge waiting' = 0 \wedge$
 $sbuffer'(waiting) = 1 \wedge sender' = 0 \wedge$
 $U(rbuffer) \wedge$
 $\forall j \in \{1, 2\} \setminus \{waiting\} : U_j(sbuffer)) \vee$

$(I = A2 \wedge sender \neq 0 \wedge sbuffer(sender) = 0 \wedge$
 $sender \neq given \wedge given = 0 \wedge$
 $given' = sender \wedge$
 $sbuffer'(sender) = 1 \wedge sender' = 0 \wedge$
 $U(waiting, rbuffer) \wedge$
 $\forall j \in \{1, 2\} \setminus \{sender\} : U_j(sbuffer)) \vee$

...

The Server

Server system $S = \langle IS, RS \rangle$.

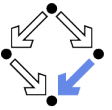
State := $(\mathbb{N}_3)^3 \times (\{1, 2\} \rightarrow \mathbb{N}_2)^2$.

Int := $\{D1, D2, F, A1, A2, W\}$.

$IS(given, waiting, sender, rbuffer, sbuffer) : \Leftrightarrow$
 $given = waiting = sender = 0 \wedge$
 $rbuffer(1) = rbuffer(2) = sbuffer(1) = sbuffer(2) = 0$.

$RS(I, \langle given, waiting, sender, rbuffer, sbuffer \rangle, \langle given', waiting', sender', rbuffer', sbuffer' \rangle) : \Leftrightarrow$
 $\exists i \in \{1, 2\} :$
 $(I = D_i \wedge sender = 0 \wedge rbuffer(i) \neq 0 \wedge$
 $sender' = i \wedge rbuffer'(i) = 0 \wedge$
 $U(given, waiting, sbuffer) \wedge$
 $\forall j \in \{1, 2\} \setminus \{i\} : U_j(rbuffer)) \vee$
 ...

$U(x_1, \dots, x_n) : \Leftrightarrow x'_1 = x_1 \wedge \dots \wedge x'_n = x_n$.
 $U_j(x_1, \dots, x_n) : \Leftrightarrow x'_1(j) = x_1(j) \wedge \dots \wedge x'_n(j) = x_n(j)$.



The Server (Contd'2)

```
Server:
  local given, waiting, sender
  begin
    given := 0; waiting := 0
    loop
      D: sender := receiveRequest()
      if sender = given then
        if waiting = 0 then
          F: given := 0
          else
            A1: given := waiting;
                waiting := 0
                sendAnswer(given)
            endif
          elsif given = 0 then
            A2: given := sender
                sendAnswer(given)
            else
              W: waiting := sender
            endif
          endloop
        end Server
```

...

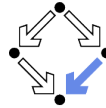
$(I = W \wedge sender \neq 0 \wedge sender \neq given \wedge given \neq 0 \wedge$
 $waiting' := sender \wedge sender' = 0 \wedge$
 $U(given, rbuffer, sbuffer)) \vee$

$\exists i \in \{1, 2\} :$

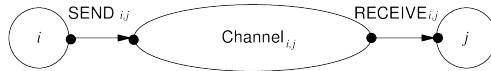
$(I = REQ_i \wedge rbuffer'(i) = 1 \wedge$
 $U(given, waiting, sender, sbuffer) \wedge$
 $\forall j \in \{1, 2\} \setminus \{i\} : U_j(rbuffer)) \vee$

$(I = ANS_i \wedge sbuffer(i) \neq 0 \wedge$
 $sbuffer'(i) = 0 \wedge$
 $U(given, waiting, sender, rbuffer) \wedge$
 $\forall j \in \{1, 2\} \setminus \{i\} : U_j(sbuffer))$.

Communication Channels

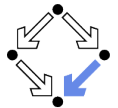


We also model the communication medium between components.

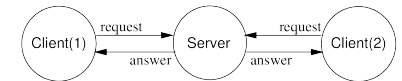


- **Bounded channel** $Channel_{i,j} = (ICH, RCH_{i,j})$.
 - Transfers message from component with address i to component j .
 - May hold at most N messages at a time (for some N).
 - $State := Value^*$.
 - Sequence of values of type $Value$.
 - $Ext := \{SEND_{i,j}(m) : m \in Value\} \cup \{RECEIVE_{i,j}(m) : m \in Value\}$.
 - By $SEND_{i,j}(m)$, channel receives from sender i a message m destined for receiver j ; by $RECEIVE_{i,j}(m)$, channel forwards that message.
- $ICH(queue) :\Leftrightarrow queue = \langle \rangle$.
 $RCH_{i,j}(l, queue, queue') :\Leftrightarrow$
 $\exists m \in Value :$
 $(l = SEND_{i,j}(m) \wedge |queue| < N \wedge queue' = queue \circ \langle m \rangle) \vee$
 $(l = RECEIVE_{i,j}(m) \wedge |queue| > 0 \wedge queue = \langle m \rangle \circ queue')$

Client/Server Example with Channels



- Server receives address 0.
 - Label REQ_i is renamed to $RECEIVE_{i,0}(R)$.
 - Label ANS_i is renamed to $SEND_{0,i}(A)$.
- Client i receives address i ($i \in \{1, 2\}$).
 - Label REQ_i is renamed to $SEND_{i,0}(R)$.
 - Label ANS_i is renamed to $RECEIVE_{0,i}(A)$.
- System is composed of seven components:
 - $Server, Client_1, Client_2$.
 - $Channel_{0,1}, Channel_{1,0}$.
 - $Channel_{0,2}, Channel_{2,0}$.



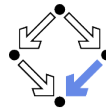
Also channels are active system components.

1. A Client/Server System

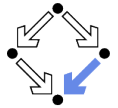
2. Modeling Concurrent Systems

3. A Model of the Client/Server System

4. Summary



Summary



- A system is described by
 - its (finite or infinite) **state space**,
 - the **initial state condition** (set of input states),
 - the **transition relation** on states.
- State space of composed system is **product of component spaces**.
 - Variable shared among components occurs only once in product.
- System composition can be
 - **synchronous**: conjunction of individual transition relations.
 - Suitable for digital hardware.
 - **asynchronous**: disjunction of relations.
 - **Interleaving** model: each relation conjoins the transition relation of one component with the identity relations of all other components.
 - Suitable for concurrent software.
- **Message passing systems** may be modeled by using labels:
 - Synchronize transitions of sender and receiver.
 - Carry values to be transmitted from sender to receiver.