# Fixpoint semantics for proximity-based logic programming

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Proximity relation *R* on an alphabet *L* s.t. the *proximity class* of any symbol ∈ *L* is finite

•  $\lambda$ -cut  $\in$  (0, 1] and a T-norm  $\wedge$ 

- ► Logic program *P* consisting of definite clauses  $A \leftarrow B_1, \ldots, B_n$ , where  $A, B_1, \ldots, B_n$  are atoms
- Semantics S = (D, I) with domain D and interpretation function I

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$$I(f) : D^n \to D$$
  
▶  $I(p) : D^n \to [0,1]$   
▶  $S(\wedge) : [0,1]^2 \to [0,1]$   
▶  $S(\leftarrow) : [0,1]^2 \to [0,1]$ 

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• variables: 
$$\llbracket x \rrbracket_S^{\sigma} = \sigma(X)$$

- ▶ atoms:  $\llbracket p(t_1, \ldots, t_n) \rrbracket_S^{\sigma} = I(p)(\llbracket t_1 \rrbracket_S^{\sigma}, \ldots, \llbracket t_n \rrbracket_S^{\sigma}) \in [0, 1]$
- ► terms:  $\llbracket f(t_1, \ldots, t_n) \rrbracket_S^{\sigma} = I(f)(\llbracket t_1 \rrbracket_S^{\sigma}, \ldots, \llbracket t_n \rrbracket_S^{\sigma}) \in D$
- conjunction of formulas:  $\llbracket F_1 \wedge F_2 \rrbracket_S^{\sigma} = \wedge_S(\llbracket F_1 \rrbracket_S^{\sigma}, \llbracket F_2 \rrbracket_S^{\sigma})$
- ▶ residual of formulas:  $\llbracket F_1 \leftarrow F_2 \rrbracket_S^{\sigma} = \leftarrow_S (\llbracket F_1 \rrbracket_S^{\sigma}, \llbracket F_2 \rrbracket_S^{\sigma})$
- ▶ all-quantor:  $\llbracket \forall x.F \rrbracket_{S}^{\sigma} = \forall_{S} \{\llbracket F \rrbracket_{S}^{\sigma\{x \to d\}} \mid d \in D\}$

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Let  $B_H$  be the Herbrand base of our program.

#### Definition

A fuzzy set  $M \in B_H \times (0,1]$  is a model of P if for every  $(A, \alpha) \in M$ ,  $[\![A]\!]_S^{\sigma} = \alpha \ge \lambda$ .

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We want to compute the *least* or *minimal Herbrand model*  $M_H$  (or *canonical model*) of a logic program, i.e. where  $\exists_M P \models M \land M \subsetneq M_H$ . If the model intersection property holds, then  $M_H := \{ \bigcap_M | P \models M \}$ .  $\subset$ ,  $\cap$  and  $\cup$  (see below) are shall be adequately defined on fuzzy sets. Given a logic program P, a proximity relation  $\mathcal{R}$  with a T-norm  $\land$  and a  $\lambda$ -cut: Which facts (i.e., elements in the Herbrand base) can we deduce and with which truth degree?

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 $\mathsf{Program} \stackrel{?}{\Longrightarrow}$ 

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 $\mathsf{Program} \stackrel{?}{\Longrightarrow} \mathsf{Canonical Model}$ 

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Intuitively, that is everything proximal to the program clauses.

Given a logic program P, a proximity relation  $\mathcal{R}$  with a T-norm  $\land$  and a  $\lambda$ -cut: Which facts (i.e., elements in the Herbrand base) can we deduce and with which truth degree?

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#### Example

Let  $a \sim_{0.7} b \sim_{0.8} c, q \sim_{0.9} r, \lambda = 0.7, \wedge = *$  and  $P = \{r(a)\}$ . Then deducible are:

- $\blacktriangleright$  r(a) with degree 1
- $\blacktriangleright$  r(b) with degree 0.7
- q(a) with degree 0.9

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#### Example

Let  $a \sim_{0.7} b \sim_{0.8} c, q \sim_{0.9} r, \lambda = 0.7, \wedge = *$  and  $P = \{r(a)\}$ . Not deducible are:

- q(b) because  $\mathcal{R}(r(a), q(b)) = 0.63 < 0.7 = \lambda$
- r(c) because  $\mathcal{R}(r(a), r(c)) = \mathcal{R}(a, c) = 0$
- q(c) because  $\mathcal{R}(r(a), q(c)) = 0$

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Intuitively, that is everything proximal to the program clauses.

#### Example

Let  $a \sim_{0.7} b \sim_{0.8} c, q \sim_{0.9} r, \lambda = 0.55, \wedge = *$  and  $P = \{r(b, b)\}$ . Then deducible are:

- $\blacktriangleright$  r(c, c) with degree 0.64
- r(a, b) with degree 0.7
- r(a, c) with degree 0.56
- q(a, b) with degree 0.63

Given a logic program P, a proximity relation  $\mathcal{R}$  with a T-norm  $\land$  and a  $\lambda$ -cut: Which facts (i.e., elements in the Herbrand base) can we deduce and with which truth degree?

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#### Example

Let  $a \sim_{0.7} b \sim_{0.8} c, q \sim_{0.9} r, \lambda = 0.55, \wedge = *$  and  $P = \{r(b, b)\}$ . Not deducible are:

- ▶ q(a, c) because  $\mathcal{R}(r(b, b), q(a, c)) = 0.504 < 0.55 = \lambda$
- ► r(a, a) because  $\mathcal{R}(r(b, b), r(a, a)) = 0.49 < 0.55 = \lambda$

Explicit notation:

$$\begin{array}{ll} r(a): & r(x) \leftarrow x \sim a \\ & q(x) \leftarrow q \sim r, x \sim a \\ r(b,b): & r(x_1,x_2) \leftarrow x_1 \sim b, x_2 \sim b \\ & q(x_1,x_2) \leftarrow q \sim r, x_1 \sim b, x_2 \sim b \end{array}$$

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where  $a \sim b$  is interpreted as  $\mathcal{R}(a, b)$ .

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where  $a \sim b$  is interpreted as  $\mathcal{R}(a, b)$ . We call this procedure *linearization* and *approximation*.

▶  $lin(p(t_1,...,t_n) \leftarrow B) = p(x_1,...,x_n) \leftarrow x_1 \sim t_1,...,x_n \sim t_n, B$  where the  $x_i$  are fresh variables

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$$\blacktriangleright Lin(P) = \{lin(c) \mid c \in P\}$$

Explicit notation:

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where  $a \sim b$  is interpreted as  $\mathcal{R}(a, b)$ . We call this procedure *linearization* and *approximation*.

$$\blacktriangleright approx(p(t_1,\ldots,t_n)\leftarrow B)=\{q(t_1,\ldots,t_n)\leftarrow p\sim q,B\}$$

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where  $a \sim b$  is interpreted as  $\mathcal{R}(a, b)$ . We call this procedure *linearization* and *approximation*.

•  $approx(p(t_1,\ldots,t_n)\leftarrow B) = \{q(t_1,\ldots,t_n)\leftarrow p\sim q,B\}$ 

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• Approx(P) = 
$$\bigcup_{c \in P} approx(c)$$

Explicit notation:

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where  $a \sim b$  is interpreted as  $\mathcal{R}(a, b)$ . We will need the *ground* instances of these clauses:

• 
$$ground(c) = \{c\theta \mid dom(\theta) = var(c), vran(\theta) = \emptyset\}$$

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• Ground(P) = 
$$\bigcup_{c \in P} ground(c)$$

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where  $a \sim b$  is interpreted as  $\mathcal{R}(a, b)$ .

$$Lin(P) = \{ lin(c) \mid c \in P \}$$

• Approx
$$(P) = \bigcup_{c \in P} approx(c)$$

• 
$$Ground(P) = \bigcup_{c \in P} ground(c)$$

Then we call Ground(Approx(Lin(P))) the extended program  $\Pi(P)$ 

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Let *H* be a Herbrand interpretation and  $\Pi$  an extended program. Then the *immediate consequence operator* is defined as follows:

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$$T_{P}(H) = \{ (A, \alpha) \mid A \leftarrow B_{1}, \dots, B_{n} \in \Pi(P), \\ \alpha = \beta_{1} \land \dots \land \beta_{n}, \\ (B_{1}, \beta_{1}), \dots, (B_{n}, \beta_{n}) \in H, \\ \} \cup H$$

Let *H* be a Herbrand interpretation and  $\Pi$  an extended program. Then the *immediate consequence operator* is defined as follows:

$$T_{P}(H) = \{ (A, \alpha) \mid A \leftarrow B_{1}^{i}, \dots, B_{n_{i}}^{i} \in \Pi(P), \\ \alpha = \sup_{i} \{ \beta_{1}^{i} \wedge \dots \wedge \beta_{n_{i}}^{i} \}, \\ (B_{1}^{i}, \beta_{1}^{i}), \dots, (B_{n_{i}}^{i}, \beta_{n_{i}}^{i}) \in H, \\ 1 \leq i \leq k \} \cup H$$

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#### Immediate consequence operator

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We instantiate the starting Herbrand interpretation  $H_0$  with

$$\{(I \sim I', \mathcal{R}(I, I') \mid I, I' \in \mathcal{L}, \mathcal{R}(I, I') \geq \lambda\}.$$

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The *least fixpoint* of  $T_P$  is the smallest H s.t.  $T_P(H) = H$ . It should coincide with the *least Herbrand model* of P.

Let again  $a \sim_{0.7} b \sim_{0.5} c, q \sim_{0.8} r, \lambda = 0.4, \wedge = \min$  and  $P = \{r(a)\}.$ 

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 and  
 $P = \{r(a)\}$ . Then  $\Pi(P) =$   
 $\{(r(a) \leftarrow r \sim r, a \sim a), (q(a) \leftarrow q \sim r, a \sim a),$   
 $(r(b) \leftarrow r \sim r, b \sim a), (q(b) \leftarrow q \sim r, b \sim a),$   
 $(r(c) \leftarrow r \sim r, c \sim a), (q(c) \leftarrow q \sim r, c \sim a)\}.$ 

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 and  
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 $H_0 = \{(a \sim b, 0.7), (b \sim c, 0.5), (r \sim q, 0.8), (a \sim a, 1), (b \sim b, 1), (c \sim c, 1), (r \sim r, 1), (q \sim q, 1)\}$ .

Let again 
$$a \sim_{0.7} b \sim_{0.5} c, q \sim_{0.8} r, \lambda = 0.4, \wedge = \min$$
 and  
 $P = \{r(a)\}$ . Then  $\Pi(P) =$   
 $\{(r(a) \leftarrow r \sim r, a \sim a), (q(a) \leftarrow q \sim r, a \sim a), (r(b) \leftarrow r \sim r, b \sim a), (q(b) \leftarrow q \sim r, b \sim a), (r(c) \leftarrow r \sim r, c \sim a), (q(c) \leftarrow q \sim r, c \sim a)\}.$   
 $H_1 = T_P(H_0) = H_0 \cup \{(r(a), sup\{1 \land 1\}), (q(a), sup\{1 \land 1\}), (r(b), sup\{1 \land 0.7\}), (q(b), sup\{0.8 \land 0.7\})\}$ 

Let again 
$$a \sim_{0.7} b \sim_{0.5} c, q \sim_{0.8} r, \lambda = 0.4, \wedge = \min$$
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 $P = \{r(a)\}$ . Then  $\Pi(P) = \{(r(a) \leftarrow r \sim r, a \sim a), (q(a) \leftarrow q \sim r, a \sim a), (r(b) \leftarrow r \sim r, b \sim a), (q(b) \leftarrow q \sim r, b \sim a), (r(c) \leftarrow r \sim r, c \sim a), (q(c) \leftarrow q \sim r, c \sim a)\}$ .  
 $H_1 = T_P(H_0) = H_0 \cup \{(r(a), 1), (q(a), 0.8), (r(b), 0.7), (q(b), 0.7)\}$ 

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Let again 
$$a \sim_{0.7} b \sim_{0.5} c$$
,  $q \sim_{0.8} r$ ,  $\lambda = 0.4$ ,  $\wedge = \min$  and  
 $P = \{r(a)\}$ . Then  $\Pi(P) =$   
 $\{(r(a) \leftarrow r \sim r, a \sim a), (q(a) \leftarrow q \sim r, a \sim a),$   
 $(r(b) \leftarrow r \sim r, b \sim a), (q(b) \leftarrow q \sim r, b \sim a),$   
 $(r(c) \leftarrow r \sim r, c \sim a), (q(c) \leftarrow q \sim r, c \sim a)\}.$   
 $H_2 = T_P(H_1) = H_1 \cup \emptyset = H_1$   
Thus,  $H_1$  is the least fixpoint of  $T_P$ .

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Let now 
$$\mathcal{R}' = \mathcal{R}$$
, but  $P' = P \cup \{p(y) \leftarrow r(y)\}$ .  
•  $Lin(P') = Lin(P) \cup \{p(x) \leftarrow x \sim y, r(y)\}$   
•  $Approx(Lin(P')) = Approx(Lin(P)) \cup \{p(x) \leftarrow x \sim y, r(y)\}$   
•  $Ground(Approx(Lin(P'))) = \Pi(P') =$   
 $Ground(Approx(Lin(P))) \cup \{(p(a) \leftarrow a \sim a, r(a)),$   
 $(p(a) \leftarrow a \sim b, r(b)), (p(b) \leftarrow b \sim a, r(a)),$   
 $(p(b) \leftarrow b \sim b, r(b)), (p(b) \leftarrow b \sim c, r(c)),$   
 $(p(c) \leftarrow c \sim b, r(b)), (p(c) \leftarrow c \sim c, r(c))\}$ 

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Let now  $\mathcal{R}' = \mathcal{R}$ , but  $P' = P \cup \{p(y) \leftarrow r(y)\}$ . •  $Lin(P') = Lin(P) \cup \{p(x) \leftarrow x \sim y, r(y)\}$ •  $Approx(Lin(P')) = Approx(Lin(P)) \cup \{p(x) \leftarrow x \sim y, r(y)\}$ •  $Ground(Approx(Lin(P'))) = \Pi(P') =$   $Ground(Approx(Lin(P))) \cup \{(p(a) \leftarrow a \sim a, r(a)),$   $(p(a) \leftarrow a \sim b, r(b)), (p(b) \leftarrow b \sim a, r(a)),$   $(p(b) \leftarrow b \sim b, r(b)), (p(b) \leftarrow b \sim c, r(c)),$   $(p(c) \leftarrow c \sim b, r(b)), (p(c) \leftarrow c \sim c, r(c))\}$  $H'_0 = H_0 \cup \{(p \sim p, 1)\}$  and

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•  $Approx(Lin(P')) = Approx(Lin(P)) \cup \{p(x) \leftarrow x \sim y, r(y)\}$   
•  $Ground(Approx(Lin(P'))) = \Pi(P') =$   
 $Ground(Approx(Lin(P))) \cup \{(p(a) \leftarrow a \sim a, r(a)), (p(a) \leftarrow a \sim b, r(b)), (p(b) \leftarrow b \sim a, r(a)), (p(b) \leftarrow b \sim a, r(a)), (p(b) \leftarrow b \sim b, r(b)), (p(b) \leftarrow b \sim c, r(c)), (p(c) \leftarrow c \sim b, r(b)), (p(c) \leftarrow c \sim c, r(c))\}$   
 $H'_0 = H_0 \cup \{(p \sim p, 1)\}$  and  
 $H'_1 = H'_0 \cup \{(r(a), 1), (r(b), 0.7), (q(a), 0.8), (q(b), 0.7)\}.$ 

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Let now 
$$\mathcal{R}' = \mathcal{R}$$
, but  $P' = P \cup \{p(y) \leftarrow r(y)\}$ .  
•  $Lin(P') = Lin(P) \cup \{p(x) \leftarrow x \sim y, r(y)\}$   
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 $H'_2 = T_P(H'_1) = H'_1 \cup \{(p(a), sup\{1 \land 1, 0.7 \land 0.7\}), (p(c), sup\{0.5 \land 0.7\})\}$ 

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 $(p(a) \leftarrow a \sim b, r(b)), (p(b) \leftarrow b \sim a, r(a)),$   
 $(p(b) \leftarrow b \sim b, r(b)), (p(b) \leftarrow b \sim c, r(c)),$   
 $(p(c) \leftarrow c \sim b, r(b)), (p(c) \leftarrow c \sim c, r(c))\}$   
 $H'_2 = T_P(H'_1) = H'_1 \cup \{$   
 $(p(a), 1),$   
 $(p(b), 0.7),$   
 $(p(c), 0.5)$   
}

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#### Definition

Let A, A' be atoms and Q, G be conjunctions of atoms. Then

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$$\leftarrow A', G \Longrightarrow_{WSLD}^{C,\sigma,\beta} \leftarrow (Q,G)\sigma$$

is a weak SLD-resolution step, where

$$C = A \leftarrow Q \in P$$
  

$$\sigma = wmgu(A, A')$$
  

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We say that a pair  $(A, \alpha)$  is provable from the program P, i.e.  $P \vdash (A, \alpha)$ , iff  $\leftarrow A \Longrightarrow_{WSLD}^{*, \alpha} \square$ .

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We say that a pair  $(A, \alpha)$  is provable from the program P, i.e.  $P \vdash (A, \alpha)$ , iff  $\leftarrow A \Longrightarrow_{WSLD}^{*,\alpha} \square$ .  $\{(A, \alpha) | P \vdash (A, \alpha)\}$  should again coincide with the least Herbrand model.