THE MACHINE LEARNING PROBLEM

A Bird's-Eye View



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Sources



What is the core problem solved by ML and what is the basic solution strategy?

The ML Problem

Automatically generate a program that solves a problem specified by (input, output) examples.

- **Given:** a sequence $T \in Pr^* \subseteq (I \times O)^*$ of (input, output) examples
 - Pr: the problem, i.e., the set of all legal (input, output) pairs from domains I and O
 - * such that
 - T (the training set) is "representative" for Pr.
- Find: a model M
 - A finitary representation of a function $[M]: I \rightarrow O$

such that M makes "good" predictions for the inputs in T, i.e., we have

 $P(M^*(T)) > p.$

- $P: (O \times O)^* \to \mathbb{R}$: the performance measure, $p \in \mathbb{R}$: the desired performance
- $M^*(T) := [(\hat{y}, y) \mid (x, y) \leftarrow T, \hat{y} = [\![M]\!](x)]$
 - x: the input, y: the output (target), \hat{y} : the prediction.
- **Test:** for candidate *M*, choose *test set* $U \in Pr^*$ "disjoint" from *T* and check $P(M^*(U)) > p$:
 - If the check succeeds, then *M* "generalizes" to the test set and is accepted.
 - If not, then M "overfits" the training set and is rejected.

If the model generalizes to the test set, it may also generalize to the full problem.

The ML Meta-Problem

To solve the ML problem, we typically have to solve the following "meta-problem".

- Given: $T \in Pr^* \subseteq (I \times O)^*$.
- Find: a model (template) $MT^{hp}[\theta]$, values \overline{hp} and $\overline{\theta}$ for its hyperparameters and parameters.
 - $hp \in HP^*$: the model *hyperparameters*.
 - $\theta \in \mathbb{R}^*$: the (numerical) model *parameters* (*weights*).

such that we have $P(M^*(T)) > p$ where

•
$$\overline{MT}[\theta] = MT^{\overline{hp}}[\theta]$$

• $M = \overline{MT}[\overline{\theta}]$

We have to find a suitable model (template), suitable values for its hyperparameters, and suitable values for its parameters.

The ML Meta-Problem (Refined)

The problem of finding suitable values for the model parameters can be framed as a problem of numerical optimization.

- Given: $T \in Pr^* \subseteq (I \times O)^*$.
- Find: a model (template) $MT^{hp}[\theta]$, values \overline{hp} for its hyperparameters, and a loss function L.
 - $L: (O \times O)^* \to \mathbb{R}$: maps a list of pairs (\hat{y}, y) to a numerical *loss* (*cost*, *error*).
 - Strongly correlated (but not necessarily identical) to the negation of P.

such that we have $P(M^*(T)) > p$ where

- $\circ \ \overline{MT}[\theta] = MT^{\overline{hp}}[\theta]$
- $\bar{\theta}$ is a value for θ that minimizes $L[(\bar{y}, y) | (x, y) \leftarrow T, \bar{y} = [\overline{MT}[\theta]](x)]$
- $M = \overline{MT}[\overline{\theta}]$

We have to select a suitable loss function and minimize it.

The ML Meta-Problem (Training/Model Fitting)

But then we also have to decide how to solve the minimization problem.

- Given: $T \in Pr^* \subseteq (I \times O)^*$.
- Find: a model (template) $MT^{hpm}[\theta]$, values \overline{hpm} for its hyperparameters, a loss function L, a training algorithm ("optimizer") TA^{hpt} , and values \overline{hpt} for its hyperparameters
 - *TA*^{*hpt*}: a function that (approximately) solves the minimization problem.

such that we have $P(M^*(T)) > p$ where

•
$$\overline{MT}[\theta] = MT^{hpm}[\theta]$$

• $\overline{\theta} = TA^{\overline{hpt}}(\overline{MT}[\theta], L, T)$ ("training the model")
• $M = \overline{MT}[\overline{\theta}]$

We have to select an appropriate algorithm for solving the minimization problem and suitable values for its hyperparameters.

The ML Meta-Problem (Validation/Hyperparameter Tuning)

It remains to choose suitable values \overline{hpm} , \overline{hpt} ,... such that the resulting model most likely generalizes well to the test set (and the full problem)...

- Given: $T \in Pr^* \subseteq (I \times O)^*$
- Find: model M such that $P(M^*(T)) > p$
 - Let V be some "part" of T and let T' be T "without" V.
 - V: the validation set.
 - Choose as \overline{hpm} , \overline{hpt} , ... values for hpm, hpt, ... (from a set of candidates) that maximize

 $P[(\bar{y}, y) \mid (x, y) \leftarrow V, \bar{y} = \llbracket \overline{MT}[\bar{\theta}] \rrbracket(x)]$ (validating the model on *V*)

where

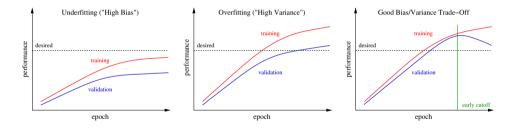
 $\overline{MT}[\theta] = MT^{hpm}[\theta]$ $\overline{a} = \overline{MT}^{hpt}(\overline{MT}[\theta] + \overline{T}^{(hpt)}(\theta) + \overline{T}^{(hpt)}(\theta)$

- $\bar{\theta} = TA^{hpt}(\overline{MT}[\theta], L, T')$ (training the model on T')
- Let $M = \overline{MT}[\overline{\theta}]$
 - \overline{MT} and $\overline{\theta}$ are determined by $\overline{hpm}, \overline{hpt}, \ldots$

We generate from the training set models for various hyperparameter combinations ("grid/ randomized search") and select the one that generalizes best to the validation set. ^{6/8}

Evaluating the Model Performance

When training the model, the optimizer runs over the training set a certain number of times ("epochs"); how do we know when the the model is adequate or can/should be further improved my more training?



Learning curves can be used to judge the adequacy of the model.

Summary

To develop an adequate machine learning model, we have to

- choose a model template,
- an optimizer,
- hyperparameters for model and optimizer,
- a loss function;
- train the model using the optimizer and loss function;
- evaluate the performance of the trained model;
- repeat the process until we have a model that neither underfits nor overfits.

Many other topics: collection and preparation of data, labeling data, model types, neural networks (architectures and training), reuse of models (transfer learning), reinforcement learning,