## Verifying Java Programs with KeY

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## Extended static checking of Java programs:

- Even if no error is reported, a program may violate its specification.
	- **Unsound calculus for verifying while loops.**
- **Exen correct programs may trigger error reports:** 
	- Incomplete calculus for verifying while loops.
	- Incomplete calculus in automatic decision procedure (Simplify).

## **No** Verification of Java programs:

- Sound verification calculus.
	- Not unfolding of loops, but loop reasoning based on invariants. п
	- Loop invariants must be typically provided by user.
- **Automatic generation of verification conditions.** 
	- From JML-annotated Java program, proof obligations are derived.
- $\blacksquare$  Human-guided proofs of these conditions (using a proof assistant).
	- **Simple conditions automatically proved by automatic procedure.**

### We will now deal with an integrated environment for this purpose.



## http://www.key-project.org

KeY: environment for verification of JavaCard programs.

- **Subset of Java for smartcard applications and embedded systems.**
- **Universities of Karlsruhe, Koblenz, Chalmers, 1998–** 
	- Beckert et al: "Deductive Software Verification The KeY Book: From Theory to Practice", Springer, 2016.
	- **n** "Chapter 16: Formal Verification with KeY: A Tutorial"
- **Specification language: JML.** 
	- **D** Original: OCL (Object Constraint Language), part of UML standard.
- **Logical framework: Dynamic Logic (DL).** 
	- Successor/generalization of Hoare Logic.
	- П Integrated prover with interfaces to external decision procedures.

 $Z$ 3, CVC4, CVC5.

Now only JML is supported as a specification language.



Further development of Hoare Logic to a modal logic.

- Hoare logic: two separate kinds of statements.
	- Formulas  $P$ , Q constraining program states.
	- Hoare triples  $\{P\} C \{Q\}$  constraining state transitions.
- Dynamic logic: single kind of statement.

Predicate logic formulas extended by two kinds of modalities.

$$
[C]Q (\Leftrightarrow \neg \langle C \rangle \neg Q)
$$

- Every state that can be reached by the execution of C satisfies Q.
- The statement is trivially true, if C does not terminate.

$$
\blacksquare \langle C \rangle Q \; (\Leftrightarrow \neg [C] \neg Q)
$$

- There exists some state that can be reached by the execution of C and that satisfies Q.
- $\blacksquare$  The statement is only true, if C terminates.

### States and state transitions can be described by DL formulas.



Hoare triple  $\{P\}C\{Q\}$  can be expressed as a DL formula.

- Partial correctness interpretation:  $P \Rightarrow [C]Q$ 
	- If P holds in the current state and the execution of C reaches another state, then Q holds in that state.
	- **Equivalent to the partial correctness interpretation of**  $\{P\}C\{Q\}$ .
- Total correctness interpretation:  $P \Rightarrow \langle C \rangle Q$ 
	- If P holds in the current state, then there exists another state that can be reached by the execution of  $C$  in which  $Q$  holds.
	- If C is deterministic, there exists at most one such state; then equivalent to the total correctness interpretation of  $\{P\}C\{Q\}$ .

For deterministic programs, the interpretations coincide.



Modal formulas can also occur in the context of quantifiers.

- Hoare Logic:  $\{x = a\}$  y:=x\*x  $\{x = a \wedge y = a^2\}$ 
	- Use of free mathematical variable a to denote the "old" value of  $x$ .

■ Dynamic logic: 
$$
\forall a : x = a \Rightarrow [y:=x*x] \ x = a \land y = a^2
$$

Quantifiers can be used to restrict the scopes of mathematical variables across state transitions.

Set of DL formulas is closed under the usual logical operations.



## A core language of commands (non-deterministic):

- $X := T$  ... assignment  $C_1$ :  $C_2$  ... sequential composition  $C_1 \cup C_2$  ... non-deterministic choice C ∗ . . . iteration (zero or more times)  $F$ ? ... test (blocks if  $F$  is false)
- A high-level language of commands (deterministic):



A calculus is defined for dynamic logic with the core command language.

# A Calculus for Dynamic Logic



### **Basic rules:**

- Rules for predicate logic extended by general rules for modalities.
- Command-related rules:

\n- \n
$$
\frac{\Gamma \vdash F[T/X]}{\Gamma \vdash [X := T]F}
$$
\n
\n- \n
$$
\frac{\Gamma \vdash [C_1][C_2]F}{\Gamma \vdash [C_1; C_2]F}
$$
\n
\n- \n
$$
\frac{\Gamma \vdash [C_1]F \quad \Gamma \vdash [C_2]F}{\Gamma \vdash [C_1 \cup C_2]F}
$$
\n
\n- \n
$$
\frac{\Gamma \vdash F \Rightarrow [C]^F}{\Gamma \vdash F \Rightarrow [C^*]F}
$$
\n
\n- \n
$$
\frac{\Gamma \vdash F \Rightarrow G}{\Gamma \vdash [F^2]G}
$$
\n
\n

From these, Hoare-like rules for the high-level language can be derived.



Calculus has to deal with the pointer semantics of Java objects.

- Aliasing: two variables  $o, o'$  may refer to the same object.
	- Field assignment  $o.a := T$  may also affect the value of  $o'.a$ .
- Update formulas:  $\{o.a \leftarrow T\}F$ 
	- **T** Truth value of F in state after the assignment  $o.a := T$ .
- Field assignment rule:

$$
\frac{\Gamma \vdash \{o.a \leftarrow T\}F}{\Gamma \vdash [o.a := T]F}
$$

Field access rule:

$$
\frac{\Gamma,o=o' \vdash F(T) \quad \Gamma,o \neq o' \vdash F(o'.a)}{\Gamma \vdash \{o.a \leftarrow T\}F(o'.a)}
$$

Case distinction depending on whether  $o$  and  $o'$  refer to same object.

■ Only applied as last resort (after all other rules of the calculus).

## Considerable complication of verifications.

## The KeY Prover



### $>$  KeY &



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File/Load Example/Getting Started/Sum and Max

```
class SumAndMax {
  int sum; int max;
  /*@ requires (\forall int i;
    @ 0 <= i && i < a.length; 0 <= a[i]);
@ 0 <= i && i < k; a[i] <= max)
    @ assignable sum, max;
    @ ensures (\forall int i;
    0 \leq i & i \leq a. length; a[i] \leq max; 0 \leq a@ ensures (a.length > 0 ==)@ (\exists int i;
    0 \leq i \& i \leq a.length;@ max == a[i]);
    @ ensures sum == (\sum int i;
    0 \leq t = i & i \leq a. length; a[i];
    @ ensures sum <= a.length * max;
   @*/
 void sumAndMax(int[] a) {
    sum = 0:
   max = 0;
    int k = 0:
                                            /*@ loop_invariant
                                              @0 \le k \& k \le a.length@ && (\forall int i;
                                              @ k& (k == 0 == > max == 0)@ k& (k > 0 == > (\exists0 \le i \& k \ne i \le k; \text{max} == a[i])@ && sum == (\sum int i;
                                              0 \leq i \& i \leq k; a[i])
                                              @ k& sum <= k * max;@ assignable sum, max;
                                              @ decreases a.length - k;
                                              @*while (k < a.length) {
                                              if (max < a[k]) max = a[k];sum += a[k]:
                                              k++:
                                            } } }
```
# A Simple Example (Contd)





### Generate the proof obligations and choose one for verification.

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# A Simple Example (Contd'2)





### The proof obligation in Dynamic Logic.



Two lists of formulas separated by a horizontal line.

 $A<sub>1</sub>$ . . .  $A_n$  $B<sub>1</sub>$ . . .  $B_m$ 

- Interpretation:  $(A_1 \wedge \ldots \wedge A_n) \Rightarrow (B_1 \vee \ldots \vee B_m)$ .  $\mathcal{L}_{\mathcal{A}}$ 
	- Proof is completed if some  $A_i$  is false or some  $B_j$  is true.
- All formulas are *unnegated*:

$$
\blacksquare (A_1 \land \neg A_2) \Rightarrow (B_1 \lor B_2) \leadsto A_1 \Rightarrow (B_1 \lor B_2 \lor A_2)
$$

$$
\blacksquare (A_1 \land A_2) \Rightarrow (B_1 \lor \neg B_2) \rightsquigarrow (A_1 \land A_2 \land B_2) \Rightarrow B_1
$$

A formula below the line may represent a "negated assumption"; a formula above the line may represent a "negated goal":

# A Simple Example (Contd'3)



```
==>
      wellFormed(heap)
    & ...
    & (( \forall int i;
             ((0 \leq i \& i \leq a.length) \& inInt(i) \Rightarrow 0 \leq a[i])k ((self_25.<inv> k (!a = null)))))
 -> {heapAtPre_0:=heap || _a:=a}
      \lambda < 1exc_25=null;try {
             self 25.sumAndMax( a)@SumAndMax;
           } catch (java.lang.Throwable e) { exc_25=e; }
         }\> ( (\forall int i;
                    ( (0 \le i \& i \le a.length) \& inInt(i) \rightarrow a[i] \le self(25.max)k (( ( a.length > 0-> \exists int i;
                            (( (0 \le i \le i \le a.length) \ge inInt(i) \ge self 25.max = a[i])))
                   & (( self_25.sum = javaCastInt(bsum{int i;}(0, a.length, a[i])) <br> & (( self 25.sum <= javaMulInt(a.length, self 25.max)
                                  self (25.sum \le javaMulInt(a.length, self 25.max)
                            & self_25.<inv>)))))))
              & (exc 25 = null)
              & \forall Field f;
                   \forall java.lang.Object o;
                                      \{ (self\ 25, SumAndMax::\$sum) \}\cup {(self 25, SumAndMax::$max)}
                       | \cdot |_0 = \text{null}& !o.<created>@heapAtPre_0 = TRUE
                       | o.f = o.f@heapAtPre 0))
```
### Press button "Start/stop automated proof search" (green arrow).

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# A Simple Example (Contd'4)





### The proof runs through automatically.

## Linear Search



```
/*@ requires a != null;
  @ assignable \nothing;
  @ ensures
  @ (\result == -1 &&
  @ (\forall int j; 0 \leq j && j \leq a.length; a[j] := x)) || \leq 0 (0 \leq \result && \result \leq a length && a[\result] == x &
      (0 <= \result && \result < a.length && a[\result] == x &&
  \mathbb{O} (\forall int j; 0 \leq j && j \leq k \result; a[j] != x));
  @*/
public static int search(int[] a, int x) {
  int n = a.length; int i = 0; int r = -1;
  /*@ loop_invariant
    @ a != null && n == a.length && 0 <= i && i <= n &&
    @ (\forall int j; 0 <= j && j < i; a[j] != x) &&
    ( (r == -1) | (r == i & k & i < n & k & a[r] == x));@ decreases r == -1 ? n-i : 0;
    @ assignable r, i; // required by KeY, not legal JML
    @*/
  while (r == -1 && i < n) {
    if (a[i] == x) r = i; else i = i+1;
  }
  return r;
}
```
## Linear Search (Contd)





### Also this verification is completed automatically.

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# Proof Structure





Multiple conditions (Taclet option "javaLoopTreatment::teaching"):

- **Invariant Initially Valid.**
- **Body Preserves Invariant.**
- Use Case (on loop exit, invariant implies postcondition).
- If proof fails, elaborate which part causes trouble and potentially correct program, specification, loop annotations.

For a successful proof, in general multiple iterations of automatic proof search (button "Start") and invocation of separate SMT solvers required (button "Run CVC5").

# Summary



**E** Various academic approaches to verifying Java(Card) programs.

- Jack: http://www-sop.inria.fr/everest/soft/Jack/jack.html
- VeriFast: https://github.com/verifast/
- **Narious tools for byte code verification.**
- Do not yet scale to verification of full Java applications.
	- General language/program model is too complex.
	- **Simplifying assumptions about program may be made.**
	- **Possibly only special properties may be verified.**
- Nevertheless very helpful for reasoning on Java in the small.
	- **Much beyond Hoare calculus on programs in toy languages.**
	- **Probably all examples in this course can be solved automatically by** the use of the KeY prover and its integrated SMT solvers.
- **Enforce clearer understanding of language features.** 
	- Perhaps constructs with complex reasoning are not a good idea...

In a not too distant future, customers might demand that some critical code is shipped with formal certificates (correctness proofs). . .