

# Automatic Refinement of Model Transformations 

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## Traditional Model Transformation Development Process <br> software competence center hagenberg



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- Aid model transformation development
- Reduce the number and the effort of the modify/correct cycles
- In most of the cases the modifications are trivial
- Support web page designers

■ Support retargeting information to different format
■.g.: Source Code to Documentation

- Results may be useful in other application
- Automatic inference of simple transformations
- Automatic inference of domain meta-model changes
- Quality evaluation of the transformations


## The Model Transformation Modification Problem

## We have

- a transformation (t) which generates code G from the source domain $S$,
■ set of examples (pairs of source models $S_{k}$ and generated codes $G_{k}$ ),


## modified code G.' corresnondina to each examnles

```
drop procedure sp_{$TbIName}_select_by_id
GO
CREATE PROCEDURE sp_${TbIName}_select_by_id
    @${TbIName}ID BIGINT
AS
    SELECT
        ${TbIName}ID,
        #foreach($ColumnName in $TblColumnNames)
        ${TbIName}${ColumnName}#if(last!=True),#end
        #end
        FROM tbl_${TbIName}
        WHERE ${TbIName}ID = @${TbIName}ID
GO
        WHERE ItemMasterID = @ItemMasterID
```

drop procedure sp_ItemMaster_select_by_id
GO
CREATE PROCEDURE sp_ItemMaster_select_by_id
@ItemMasterID BIGINT
AS
SELECT
ItemMasterID,
ItemMasterNumber,
ItemMasterDesc1,
ItemMasterDesc2,
ItemMasterProductTypeRef,
ItemMasterPartTypeRef,
ItemMasterRemark
FROM tbl_ItemMaster
WHERE ItemMasterID = @ItemMasterID

- Direction (Inspired by grammatical inference)

■ Developing specialized algorithms (instead of using generic optimization methods e.g. Genetic Algorithms)

- Define measures to judge the quality of a refinement algorithms
Evaluate different versions of the algorithms
- Steps (Inspired by type checking solutions of XMLs)
- Examine finite state (string) transducers
- To investigate modification by example paradigm

■ Experiment "XSLT" like languages

- To experiment "industrial" examples


## The Example



■ Input: „aabaaba"
■ Output: „xyywzxywz"
■ Expected output: „xyyvzxyvz"

## The Algorithm

- Used data types:
- TransitionKey := (source: State, input: Input)
- TransitionData := (target: State, output: Output)

■ Rules := TransitionKey $\rightarrow$ TransitionData
■ Transducer := (input: set(Input), output: set(Output), state: set(State), init: State, rules: Rules)

- TraceStep := (source: State, input: Input, target: State, output: Output)
- Trace := TraceStep*
- Diff := (output: Output, mod: \{' ', '-', '+'\})*

```
inferTransducer(Transducer trans, Input* input, Output* output'):Transducer
    Trace tr=execute(trans,input)
    Output* output=getOutput(tr)
    Diff diff=calculateDiff(output,output')
    Trace tr'=modifyTrace(tr, diff, trans.init)
    Transducer trans'=modifyTransducer(trans, tr')
    return trans'
```


## The Data-flow of the Example Problem



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## Modifying the transducer

modifyTransducer(Transducer, Trace'):Transducer

- If the transition in the modified trace is possible according to transition of the transducer:
- Count the usage of the transition
- If it is not possible:
- Add the new transition to the existing ones (only if the transition not destroy deterministic behaviour)
■ or modify an existing transition (this is the tricky part)


## Modify an Existing Transition

- Modification of an existing transition (a simple version):
- Modify the transition from the trace with a new 'start state'
- Modify the 'end state' of the preceding transition (corresponding to the preceding trace element) to the new state
- If the transition is executed only once according to trace, we are done; Otherwise we have to modify all transitions corresponding to the preceding trace elements, until we do not find an transition executed only once


## We may create several slightly different versions of the algorithm

## Measuring the Efficiency of the Algorithm

Compare the result of the algorithm with a hand crafted expected result

- Structural metrics of the transducer modification

■ Number of new states

- Number of new/modified transitions
- Behavioural metrics of the transducer modification
- Difference in behaviour between the original transducer and modified transducer
- Metrics of the relation between the transducers and the examples
Coverage of the transitions

First experiments: basic metrics do not help to explain the results of the manual inspection of the results. Why?

## Goal-Question-Metric Paradigm

- Goal

■ Evaluate how efficiently the examples describe the modification intention of the user

- Questions
- How many possible interpretations of the example are possible? (How clear is the intention of the user?)
- Are the examples minimal?
- Are the examples consistent?
- Metrics

Branches and cycles in the execution graph of the transducers

- Possible interpretations of the examples


## "Metrics of Intentions"

- Inserting a new edge into the graph:

■ Existing examples (possible sate transitions)
■ No iteration: xnz

$$
A, x, 1, n, B, z / A, x, B, n, 1, z
$$

■ One iteration: xnyz
$A, x, 1, n, B, y, B, z / A, x, B, n, 1, y, B, z$

- Two iterations: xnyyz

$$
A, x, 1, n, B, y, B, y, B, z
$$



| Modification <br> Intention | Examples | Possible <br> Interpretations | Intuition | Clarity |
| :--- | :--- | :--- | :--- | :---: |
| Before the cycle | No iteration | Before the cycle | Yes | $1 / 2$ |
|  |  | After the cycle | Yes | $1 / 2$ |
|  | One iteration | Before the cycle | Yes | $1 / 2$ |
|  |  | In the beginning <br> of the cycle | Yes | $1 / 2$ |
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## The Concepts Behind the New Algorithm

- The idea is to replace the "modifyTrace" function with a new one which
- Does not modify the trace, but annotates the transducer
- The annotations contains the possible way of the modification
- Then the "modifyTransducer" will consolidate these annotations
- The modification intention is clear
- The modification intention is not clear
- The annotations are contradicting


## Applying the Algorithm to Transformation Languages

- Main differences in execution:
- Transducers: selection of the transition depend on the input string
- Transformation languages: selection of the execution path depends on the input data and the result of computed values
$\square$ Main differences in print instruction:
- Transducers: always a fixed constant
- Transforamtion languages: can be any computed values

- Conclusions
- We described an algorithm to infer transducer modifications
- We described the concepts of a more powerful modification inference algorithm and its application concepts to transformation languages
- We defined metrics to evaluate such algorithms
- Further work
- Compare the algorithms

