

Alloy - Part II

Dynamic Models and Automation

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06.03.2015

Outline

Dynamic Modeling

Translation of a First-Order Formula to a Quantifier-free
Boolean Formula

Section 1

Dynamic Modeling

Static vs Dynamic Modeling

- ▶ Static models
 - ▶ Describe states (file system)
- ▶ Dynamic models
 - ▶ Describe transitions between states

Example - River Crossing Part I

```
/* Impose an ordering on the State. */
open util/ordering[State]

/* Farmer and his possessions are objects. */
abstract sig Object { eats: set Object }
one sig Farmer, Fox, Chicken, Grain extends Object {}

/* Defines what eats what and the farmer is not around. */
fact { eats = Fox->Chicken + Chicken->Grain}

/* Stores the objects at near and far side of river. */
sig State { near, far: set Object }

/* In the initial state, all objects are on the near side. */
fact { first.near = Object && no first.far }

/* At most one item to move from 'from' to 'to' */
pred crossRiver [from, from', to, to': set Object] {
  one x: from | {
    from' = from - x - Farmer - from'.eats
    to' = to + x + Farmer
  }
}
```

Example - River Crossing Part II

```
/* crossRiver transitions between states */
fact {
  all s: State, s': s.next {
    Farmer in s.near =>
      crossRiver [s.near, s'.near, s.far, s'.far]
    else
      crossRiver [s.far, s'.far, s.near, s'.near]
  }
}

/* the farmer moves everything to the far side of the river. */
run { last.far=Object } for exactly 8 State
```

Section 2

Translation of a First-Order Formula to a Quantifier-free Boolean Formula

Subsection 1

Introduction

Introduction

Automatic analysis for relational logic:

Input:

Formula and scope

Output:

Checks whether a model exists and if so returns it

- ▶ Undecidable
- ▶ Can be used in 2 ways:
 - ▶ Check consistency of a formula
 - ▶ Check validity of a theorem

Overview

- ▶ Syntax
- ▶ Semantics
- ▶ Analysis
- ▶ Performance
- ▶ Future work

Syntax

problem ::= decl* formula

decl ::= var : typexpr

typexpr ::=

type	set
 type -> type	relation
 type => typexpr	function

formula ::=

expr in expr	subset
 ! formula	negation
 formula && formula	conjunction
 formula formula	disjunction
 all v : type formula	universal
 some v : type formula	existential

expr ::=

 expr + expr	union
 expr & expr	intersection
 expr - expr	difference
 expr . expr	navigation
 ~ expr	transpose
 + expr	closure
 {v : t formula}	comprehension
 Var	

Var ::=

 var	variable
 Var [var]	application

Semantics

$M : \text{formula} \rightarrow \text{env} \rightarrow \text{boolean}$
 $X : \text{expr} \rightarrow \text{env} \rightarrow \text{value}$
 $\text{env} = (\text{var} + \text{type}) \rightarrow \text{value}$
 $\text{value} = \mathcal{P}(\text{atom} \times \text{atom}) + (\text{atom} \rightarrow \text{value})$

$M[a \text{ in } b] e = X[a] e \subseteq X[b] e$
 $M[! F] e = \neg M[F] e$
 $M[F \ \&\& \ G] e = M[F] e \wedge M[G] e$
 $M[F \ || \ G] e = M[F] e \vee M[G] e$
 $M[\text{all } v : t \ | \ F] e = \wedge \{M[F](e \oplus v \mapsto x) \mid (x, \text{unit}) \in e(t)\}$
 $M[\text{some } v : t \ | \ F] e = \vee \{M[F](e \oplus v \mapsto x) \mid (x, \text{unit}) \in e(t)\}$

$X[a + b] e = X[a] e \cup X[b] e$
 $X[a \ \& \ b] e = X[a] e \cap X[b] e$
 $X[a - b] e = X[a] e \setminus X[b] e$
 $X[a . b] e = \{(x, z) \mid \exists y. (y, z) \in X[a] e \wedge (y, x) \in X[b] e\}$
 $X[\sim a] e = \{(x, y) \mid (y, x) \in X[a] e\}$
 $X[+a] e = \text{the smallest } r \text{ such that } r ; r \subseteq r \wedge X[a] e \subseteq r$
 $X[(v : t \ | \ F)] e = \{(x, \text{unit}) \in e(t) \mid M[F](e \oplus v \mapsto x)\}$
 $X[v] e = e(v)$
 $X[a[v]] e = (e(a))(e(v))$

Example

`all x:X | some y:Y | x.r = y`

Subsection 2

Analysis

5 Steps of Analysis

- ▶ Conversion to negation normal form and skolemization
- ▶ Translation
- ▶ Conversion to CNF
- ▶ Handover to SAT solver
- ▶ Construction of a model of the relational formula

Normalization of the Relational Formula

- ▶ Convert to NNF (negation normal form)
- ▶ Skolemize it

Example

!all x: X | **some** y: Y | x.r=y

some x: X | **all** y: Y | !x.r=y

all y: Y | !x.r=y

some z: X | z=x

Overview of the Translation

Input:

Relational formula

Output:

Boolean formula for a given scope

- ▶ Represent relations as matrices of boolean values
- ▶ Constraints on relations can be expressed as boolean formulas

Translation Rules

MT : formula \rightarrow booleanFormula tree

XT : expr \rightarrow value tree

a tree = (var \times (index \rightarrow a tree)) + a

value = booleanFormulaMatrix + (index \rightarrow value)

MT [a in b] = merge (MT[a], MT[b], $\lambda p.q. \wedge_i \{p_i \Rightarrow q_i\}$)

MT [! f] = map (MT[f], \neg)

MT [f && g] = merge (MT[f], MT[g], \wedge)

MT [f || g] = merge (MT[f], MT[g], \vee)

MT [all v: t | f] = fold (MT[f], \wedge)

MT [some v: t | f] = fold (MT[f], \vee)

XT [a + b] = merge (XT[a], XT[b], $\lambda p,q.\mu r. r_i = p_i \vee q_i$)

XT [a & b] = merge (XT[a], XT[b], $\lambda p,q.\mu r. r_i = p_i \wedge q_i$)

XT [a - b] = merge (XT[a], XT[b], $\lambda p,q.\mu r. r_i = p_i \wedge \neg q_i$)

XT [a . b] = merge (XT[a], XT[b], $\lambda p,q.\mu r. r_i = \exists k. p_k \wedge q_k$)

XT [~a] = map (XT[a], $\lambda p.(r | r_i = p_i)$)

XT [+a] = map (XT[a], closure)

XT [(v: t | f] = fold (MT[f], $\lambda f. \mu r. r_a = f(i)$)

XT [a[v]] = merge (XT[a], XT[v], $\lambda s,x. \mu s, x_p. x_p$)

XT [v] = (v, $\lambda i. (\mu r. r_a = (i = j))$)

XT [v] = create (v)

when v is quantified
otherwise

merge : a tree, a tree, (a,a \rightarrow β) \rightarrow β tree

merge (x, y, o) = o(x, y)

merge ((u,t1), (u,t2), o) = (u, $\lambda i. \text{merge}(t1(i),t2(i),o)$)

merge ((u,t1), (v,t2), o) = (u, $\lambda i. \text{merge}(t1(i),(v,t2),o)$) when $u < v$

merge ((u,t1), (v,t2), o) = (v, $\lambda i. \text{merge}((u,t1),t2(i),o)$) when $v < u$

merge ((u,t), y, o) = (u, $\lambda i. \text{merge}(t(i),y ,o)$)

merge (x, (v,t), o) = (v, $\lambda i. \text{merge}(x,t(i),o)$)

map : a tree, (a \rightarrow a) \rightarrow a tree

map (x, o) = o(x)

map ((u,t), o) = (u, $\lambda i. \text{map}(t(i),o)$)

fold : a tree, ((index \rightarrow a) \rightarrow β) \rightarrow β tree

fold ((u,t), o) = o(t)

when t(i) elementary
otherwise

fold ((u,t), o) = (u, $\lambda i. \text{fold}(t(i),o)$)

create: var \rightarrow value

create (v) = (r | $r_a =$ a fresh boolean variable F(v,i)) for v: S

create (v) = (r | $r_a =$ a fresh boolean variable F(v,i,j)) for v: S \rightarrow T

create (v) = (r | $r_a =$ create (v)) for v: S \Rightarrow t

Example Translation

Example

`all y:Y | !x.r = y`

with a scope of 2

Conversion to CNF, Solving and Mapping Back

The following steps are:

- ▶ Convert to CNF and pass to the solver
- ▶ If a solution exists we can reconstruct a model of the relational formula

Performance

Three models originally written in NP

- ▶ Finder, a toy model for a Macintosh file system
- ▶ Style, a model of an aspect of the paragraph style mechanism of Microsoft Word
- ▶ Mobile IP, a model that exposed a flaw in an internet protocol for forwarding messages to mobile hosts

<i>Example</i>	<i>Scope</i>	<i>Space</i>	<i>Old [16]</i>	<i>New</i>
Finder	5	160 bits	3s	9s
	6	216	162s	13s
Style	3	90	1s	3s
	4	156	2s	3s
	5	250	11s	6s
Mobile IP	3	175	0s	1s
	4	280	3s	6s
	5	600	8s	29s

Future Work - KodKod

Kodkod is a new relational engine designed expressly as a plugin component that can easily be incorporated as a backend of another tool.

- ▶ Want to use Alloy as a backend engine
- ▶ Disadvantages of current implementation:
 - ▶ A clean API
 - ▶ Support for partial instances
 - ▶ A mechanism for sharing subformulas and subexpressions

References



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Automating First-Order Relational Logic